

COMBIVERT F6

INSTRUCTIONS FOR USE | **INSTALLATION F6 HOUSING 7**
HIGH SPEED DRIVE




Translation of the original manual
Document 20313557 EN 03

Preface

The hardware and software described in this document are products of KEB. The information contained in this document is valid at the time of publishing. KEB reserves the right to update this document in response to misprints, mistakes or technical changes.

Signal words and symbols

Certain procedures within this document can cause safety hazards during the installation or operation of the device. Refer to the safety warnings in this document when performing these procedures. Safety signs are also located on the device where applicable. A safety warning is marked by one of the following warning signs:

 DANGER	Dangerous situation, which will cause death or serious injury if this safety warning is ignored.
 WARNING	Dangerous situation, which may cause death or serious injury if this safety warning is ignored.
 CAUTION	Dangerous situation, which may cause minor injury if this safety warning is ignored.
NOTICE	Situation, which can cause damage to property if this safety warning is ignored.

RESTRICTION

Used when the following statements depend on certain conditions or are only valid for certain ranges of values.



Used for informational messages or recommended procedures.

More symbols

- This arrow starts an action step.
- / - Enumerations are marked with dots or indents.
- => Cross reference to another chapter or another page.



Note to further documentation.
<https://www.keb-automation.com/search>



Laws and guidelines

KEB Automation KG confirms with the EC declaration of conformity and the CE mark on the device nameplate that it complies with the essential safety requirements.

The EC declaration of conformity can be downloaded on demand via our website.

Warranty and liability

The warranty and liability on design, material or workmanship for the acquired device is given in the general sales conditions.



Here you will find our general sales conditions.

<https://www.keb-automation.com/terms-conditions>



Further agreements or specifications require a written confirmation.

Support

Although multiple applications are referenced, not every case has been taking into account. If you require further information or if problems occur which are not referenced in the documentation, you can request the necessary information via the local KEB agency.

The use of our units in the target products is outside of our control and therefore lies exclusively in the area of responsibility of the customer.

The information contained in the technical documentation, as well as any user-specific advice in spoken and written and through tests, are made to best of our knowledge and information about the intended use. However, they are regarded as being only informal and changes are expressly reserved, in particular due to technical changes. This also applies to any violation of industrial property rights of a third-party. Selection of our units in view of their suitability for the intended use must be done generally by the user.

Tests can only be done within the intended end use of the product (application) by the customer. They must be repeated, even if only parts of hardware, software or the unit adjustment are modified.

Copyright

The customer may use the instructions for use as well as further documents or parts from it for internal purposes. Copyrights are with KEB and remain valid in its entirety.

This KEB product or parts thereof may contain third-party software, including free and/or open source software. If applicable, the license terms of this software are contained in the instructions for use. The instructions for use are already available to you, can be downloaded free of charge from the KEB website or can be requested from the respective KEB contact person.

Other wordmarks or/and logos are trademarks (™) or registered trademarks (®) of their respective owners.

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1 Basic Safety Instructions

The products are designed and constructed in accordance with state-of-the-art technology and the recognized safety rules and regulations. However, the use of such devices may cause functional hazards for life and limb of the user or third parties, or damages to the system and other material property.

The following safety instructions have been created by the manufacturer for the area of electric drive technology. They can be supplemented by local, country- or application-specific safety instructions. This list is not exhaustive. Violation of the safety instructions by the customer, user or other third party leads to the loss of all resulting claims against the manufacturer.

NOTICE



Hazards and risks through ignorance!

- ▶ Read the instructions for use!
- ▶ Observe the safety and warning instructions!
- ▶ If anything is unclear, please contact KEB Automation KG!

1.1 Target group

This instruction manual is determined exclusively for electrical personnel. Electrical personnel for the purpose of this instruction manual must have the following qualifications:

- Knowledge and understanding of the safety instructions.
- Skills for installation and assembly.
- Start-up and operation of the product.
- Understanding of the function in the used machine.
- Detection of hazards and risks of the electrical drive technology.
- Knowledge of *VDE 0100*
- Knowledge of national safety regulations.

1.2 Transport, storage and proper use

The transport is carried out by qualified persons in accordance with the environmental conditions specified in this manual. Drive controller shall be protected against excessive strains.



Transport of drive controllers with an edge length >75 cm

The transport by forklift without suitable tools can cause a deflection of the heat sink. This leads to premature aging or destruction of internal components.

- ▶ Transport of drive controllers on suitable pallets.
- ▶ Do not stack drive controllers or burden them with other heavy objects.

NOTICE

Damage to the coolant connections

Bending of the tubes!

- ▶ Never place the device on the coolant connections



Drive controllers contain electrostatic sensitive components.

- ▶ Avoid contact.
- ▶ Wear ESD-protective clothing.

Do not store drive controllers

- in the environment of aggressive and/or conductive liquids or gases.
- with direct sunlight.
- outside the specified environmental conditions.

1.3 Installation

⚠ DANGER



Do not operate in an explosive environment!

- ▶ The product is not intended for the use in potentially explosive environment.

⚠ CAUTION



Design-related edges and high weight!

Contusions and bruises!

- ▶ Never stand under suspended loads.
- ▶ Wear safety shoes.
- ▶ Secure drive controller accordingly when using lifting gear.

To prevent damages to the device:

- Make sure that no components are bent and/or isolation distances are changed.
- The device must not be put into operation in case of mechanical defects.
- Do not allow moisture or mist to penetrate the unit.
- Avoid dust permeating the device. Allow for sufficient heat dissipation if installed in a dust-proof housing.
- Note installation position and minimum distances to surrounding elements. Do not cover the ventilation openings.
- Mount the drive controller according to the specified degree of protection.
- Make sure that no small parts fall into the product during assembly and wiring (drilling chips, screws etc.). This also applies to mechanical components, which can lose small parts during operation.
- Check the reliable fit of the device connections in order to avoid contact resistances and sparking.
- Do not walk-on drive controller.
- Follow all safety instructions!

1.4 Electrical connection

DANGER

Voltage at the terminals and in the device!

Danger to life due to electric shock !

- ▶ Never work on the open device or never touch exposed parts.
- ▶ For any work on the unit switch off the supply voltage, secure it against switching on and check absence of voltage by measuring at the input terminals.
- ▶ Wait until all drives has been stopped in order that no regenerative energy can be generated.
- ▶ Await capacitor discharge time (5 minutes). Check absence of voltage by measuring at the DC terminals.
- ▶ If personal protection is required, install suitable protective devices for drive converters.
- ▶ Never bridge upstream protective devices (even for testing purposes).
- ▶ Connect the protective earth conductor always to drive converter and motor.
- ▶ Install all required covers and protective devices for operation.
- ▶ The control cabinet shall be kept closed during operation.
- ▶ Residual current: This product may cause a dc current in the protective earth conductor. When a residual current protective device (RCD) or a residual current monitoring device (RCM) is used for the protection against direct or indirect contact, only a RCD or RCM type B is permitted on the power supply side of this product.
- ▶ Drive converters with a leakage current > 3.5mA AC current (10mA DC current) are intended for a stationary connection. Protective earth conductors must be designed in accordance with the local regulations for equipment with high leakage currents according to [EN 61800-5-1](#), [EN 60204-1](#) or [VDE 0100](#).



If personnel protection is required during installation of the system, suitable protective devices must be used for drive controllers.

www.keb.de/fileadmin/media/Techinfo/dr/tn/ti_dr_tn-rcd-00008_en.pdf



Installations which include drive controller shall be equipped with additional control and protective devices in accordance with the relevant applicable safety requirements, e.g. act respecting technical equipment, accident prevention rules etc. They must always be complied with, also for drive controller bearing a CE marking.

For a trouble-free and safe operation, please pay attention to the following instructions:

- The electrical installation shall be carried out in accordance with the relevant requirements.
- Cable cross-sections and fuses must be dimensioned by the user according to the specified minimum/maximum values for the application.
- Connection of the drive converter is only permissible on symmetrical networks with a maximum line voltage (L1, L2, L3) with respect to earth (N/PE) of max. 300 V, USA UL: 480 / 277 V. An isolating transformer must be used for supply networks which exceed this value! In case of non-compliance the control is not longer considered to be a PELV circuit.
- With existing or newly wired circuits the person installing the units or machines must ensure that the PELV requirements are met.
- For drive converters that are not isolated from the supply circuit (in accordance with [EN 60721-3-2](#)) all control lines must be included in other protective measures (e.g. double insulation or shielded, earthed and insulated).
- When using components without isolated inputs/outputs, it is necessary that equipotential bonding exists between the components to be connected (e.g. by the equipotential line). Disregard can cause destruction of the components by equalizing currents.

1.4.1 EMC-compatible installation

Observance of the limit values required by EMC law is the responsibility of the customer.



Notes on EMC-compatible installation can be found here.
www.keb.de/fileadmin/media/Manuals/dr/emv/0000neb0000.pdf



1.4.2 Voltage test

Testing with AC voltage (in accordance with [EN 60204-1](#) chapter 18.4) may not be executed, since there is danger for the power semiconductors in the drive controller.



Due to the radio interference suppression capacitors, the test generator will switch off immediately with a current fault.



According to [EN 60204-1](#) it is permissible to disconnect already tested components. Drive controllers of the KEB Automation KG are delivered ex works voltage tested to 100% according to product standard.

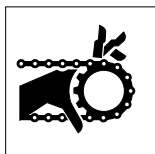
1.4.3 Insulation measurement

An insulation measurement (in accordance with [EN 60204-1](#) chapter 18.3) with DC 500 V is permissible, if all power unit connections (grid-connected potential) and all control connections are bridged with PE. The insulation resistance of the respective device can be found in the technical data.

1.5 Start-up and operation

The start-up (i.e. for the specified application) is forbidden until it is determined that the installation complies with the machine directive; account is to be taken of [EN 60204-1](#).

⚠ WARNING



Software protection and programming!

Hazards caused by unintentional behavior of the drive!

- ▶ Check especially during initial start-up or replacement of the drive controller if parameterization is compatible to application.
- ▶ Securing a unit solely with software-supported functions is not sufficient. It is imperative to install external protective measures (e.g. limit switch) that are independent of the drive controller.
- ▶ Secure motors against automatic restart.

⚠ CAUTION



High temperatures at heat sink and coolant!

Burning of the skin!

- ▶ Cover hot surfaces safe-to-touch.
- ▶ If necessary, attach warning signs on the system.
- ▶ Before touching, check the surface and coolant lines.
- ▶ Before working let the unit cool down.

- During operation, all covers and doors shall be kept closed.
- Use only approved accessories for this device.
- Never touch terminals, busbars or cable ends.

⚠ CAUTION



High sound level during operation !

Hearing damage possible!

- ▶ Wear hearing protection!

NOTICE

Continuous operation (S1) with load > 60 % or from a rated motor power of 55 kW!

Premature ageing of the electrolytic capacitors !

- ▶ Mains choke with $U_k = 4\%$ absolutely necessary.



If a drive controller with electrolytic capacitors in a DC link has not been in operation for more than one year, observe the following instructions.

www.keb.de/fileadmin/media/Techinfo/dr/tn/ti_dr_tn-format-capacitors-00009_en.pdf



Switching at the output

Switching between motor and drive controller is prohibited for single drives during operation as this may trigger the protection gear of the device. Function ‚speed search‘ must be activated if switching can not be avoided. Speed search may only be triggered after closing the motor contactor (e.g. by switching the control release).

Connecting and disconnecting is permissible with multiple motor drives if at least 1 motor is running during the switch-over process. The drive controller must be dimensioned to the occurring starting currents.

The ‚speed search‘ function must be activated if the motor is still running during a restart of the drive controller (mains on) (e.g. due to large rotating masses).

Switching at the input

For applications that require cyclic switching off and on of the drive controller, maintain an off-time of at least 5 min after the last switch on. If you require shorter cycle times please contact KEB Automation KG.

Short-circuit resistance

The drive converters are conditional short-circuit proof. After resetting the internal protection devices, the function as directed is guaranteed.

Exceptions:

- If an earth-leakage fault or short-circuit often occurs at the output, this can lead to a defect in the unit.
- If a short-circuit occurs during regenerative operation (2nd or 4th quadrant, regeneration into the DC link), this can lead to a defect in the unit.

1.6 Maintenance

The following maintenance work has to be carried out when required, but at least once per year by authorized and trained personnel. Check unit for loose screws and plugs and tighten if necessary.

- ▶ Check system for loose screws and plugs and tighten if necessary.
- ▶ Clean drive controller from dirt and dust deposits. Pay attention especially to cooling fins and protective grid of the fans.
- ▶ Examine and clean extracted air filter and cooling air filter of the control cabinet.
- ▶ Check the function of the fans of the drive controller. The fan must be replaced in case of audible vibrations or squeak.
- ▶ In the case of liquid-cooled drive controllers a visual test of the cooling circuit for leaks and corrosion must be carried out. The cooling circuit must be completely empty if a unit shall be switched off for a longer period. The cooling circuit must be blown out additionally with compressed air at temperatures below 0°C.

1.7 Repair

In case of malfunction, unusual noises or smells inform a person in charge!

DANGER



Unauthorized exchange, repair and modifications!

Unpredictable malfunctions!

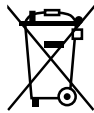
- ▶ The function of the drive controller is dependent on its parameterization. Never replace without knowledge of the application.
- ▶ Modification or repair is permitted only by KEB Automation KG authorized personnel.
- ▶ Only use original manufacturer parts.
- ▶ Infringement will annul the liability for resulting consequences.

In case of failure, please contact the machine manufacturer. Only the machine manufacturer knows the parameterisation of the used drive controller and can provide an appropriate replacement or induce the maintenance.

1.8 Disposal

Electronic devices of the KEB Automation KG are exclusively professional devices for further industrial processing (so-called B2B devices).

Manufacturers of B2B devices are obliged to take back and recycle devices manufactured after 14.08.2018. These devices may not be disposed at the collection centres of public sector disposal organisations.



If no deviating agreement has been made between the customer and KEB or no deviating mandatory legal regulation exists, KEB products marked in this way can be returned. Company and keyword to the return point can be taken from the list below. Shipping costs are paid by the customer. Thereupon the devices will be professionally recycled and disposed.

The entry numbers are listed country-specific in the following table. The corresponding KEB return addresses can be found on our website.

Withdrawal by	WEEE-Reg.-No.	Keyword
Austria		
KEB Automation GmbH	ERA: 51976	Stichwort „Rücknahme WEEE“
France		
RÉCYLUM - Recycle point	ADEME: FR021806	Mots clés „KEB DEEE“
Germany		
KEB Automation KG	EAR: DE12653519	Stichwort „Rücknahme WEEE“
Italy		
COBAT	AEE: (IT) 19030000011216	Parola chiave „Ritiro RAEE“
Spain		
KEB Automation KG	RII-AEE 7427	Palabra clave „Retirada RAEE“
Česko		
KEB Automation KG	RETELA 09281/20 ECZ	Klíčové slovo: Zpětný odběr OEEZ
Slowakei		
KEB Automation KG	ASEKOL: RV22EEZ0000421	Klíčové slovo: "Spätný odber OEEZ"

The packaging must be feed to paper and cardboard recycling.

2 Product Description

The device series COMBIVERT F6 concerns to drive controllers, which are optimized for operation at synchronous and asynchronous motors.

The COMBIVERT can be extended with a safety module for the use in safety-oriented applications. The COMBIVERT F6 series are drive converters with functional safety, optimized for operation at synchronous and asynchronous motors.

Various safety functions are available for different applications. It can be operated with a fieldbus module at different fieldbus systems. The control board has a system comprehensive operating concept.

The COMBIVERT complies with the requirements of the Machinery Directive. The possible functions are certified via a type test.

The COMBIVERT is a product of limited availability in accordance with [EN 61800-3](#). This product may cause radio interference in residential areas. In this case the operator may need to take corresponding measures.

The Machinery Directive, EMC Directive, Low Voltage Directive and other directives and regulations must be observed

2.1 Specified application

The COMBIVERT serves exclusively for the control and regulation of three-phase motors. It is intended for the installation into electrical systems or machines in the industrie.

Technical data and information for connection conditions shall be taken from the nameplate and from the instructions for use and must be strictly observed.

The used semiconductors and components of the KEB Automation KG are developed and dimensioned for the use in industrial products.

Restriction

If the product is used in machines, which work under exceptional conditions or if essential functions, life-supporting measures or an extraordinary safety step must be fulfilled, the necessary reliability and security must be ensured by the machine builder.

2.1.1 Residual risks

Despite intended use, the drive converter can reach unexpected operating conditions in case of error, with wrong parameterization, by faulty connection or unprofessional interventions and repairs. This can be:

- wrong direction of rotation
- motor speed too high
- motor is running into limitation
- motor can be under voltage even in standstill
- automatic start

2.2 Unintended use

The operation of other electric consumers is prohibited and can lead to the destruction of the devices. The operation of our products outside the indicated limit values of the technical data leads to the loss of any liability claims.

2.3 Product features

These instructions for use describe the power units of the following devices:

Device type:	Drive controller
Series:	COMBIVERT F6
Power range:	132...160 kW / 400 V (air cooler) 132...200 kW / 400V (fluid cooler water)
Housing:	7 High Speed Drive

The COMBIVERT F6 is characterized by the following features:

- Operation of three-phase asynchronous motors and three-phase synchronous motors, in operating modes open-loop or closed-loop with and without speed feedback
- Following fieldbus systems are supported:
EtherCAT, VARAN, PROFINET, POWERLINK or CAN
- System-overlapping operating concept
- Wide operating temperature range
- Low switching losses by IGBT power unit
- Low noise development due to high switching frequencies
- Different heat sink concepts
- Temperature-controlled fan, easily replaceable
- Torque limits and s-curves are adjustable to protect gearboxes
- General protection functions of the COMBIVERT series against overcurrent, over-voltage, ground fault and overtemperature
- Analog inputs and outputs, digital inputs and outputs, relay output (potential-free), brake control and -supply, motor protection by I^2t , KTY- or PTC input, two encoder interfaces, diagnostic interface, fieldbus interface (depending on the control board)
- Integrated safety function according to [EN 61800-5-2](#)

2.4 Part code

x x F 6 x x x - x x x x

Heat sink version	1:	Air-cooler, mounted version
	2:	Liquid cooler (water), mounted version
	3:	Air-cooler, through-mount version IP54-ready
	4:	Liquid cooler (water), through-mount version IP54-ready
	5:	Air-cooler, through-mount version IP20
	6:	Liquid cooler (water), through-mount version IP54-ready, sub-mounted braking resistors
	7:	Liquid cooler (oil), through-mount version IP54-ready
	9:	Liquid cooler (water), mounted version, sub-mounted braking resistors
	A:	Liquid cooler (water), mounted version, High Performance, sub-mounted braking resistors
	B:	Liquid cooler (water), through-mount version, IP54-ready, High Performance, sub-mounted braking resistors
	C:	Air-cooler, mounted version, Version 2
	D:	Air-cooler, mounted version, High-Performance
	E:	Liquid cooler (water), mounted version, High-Performance
	F:	Air-cooler, through-mount version IP54-ready, High-Performance
	G:	Liquid cooler (water), through-mount version IP54-ready, High-Performance
	H:	Air-cooler,, Convektion, through-mount version IP54-ready
Control board variant	APPLIKATION	
	1:	Multi Encoder Interface, CAN ^{® 2)} , Real-Time Ethernet-busmodule ³⁾
	B	Multi Encoder Interface, CAN ^{® 2)} , Real-Time Ethernet-busmodule ³⁾ , Alternative connector
	KOMPAKT	
	1:	Multi Encoder Interface, CAN ^{® 2)} , STO, EtherCAT ^{® 1)}
	2:	Multi Encoder Interface, CAN ^{® 2)} , STO, VARAN
	PRO	
	0:	No Encoder, CAN ^{® 2)} , Real-Time Ethernetinterface ³⁾
	1:	Multi Encoder Interface, CAN ^{® 2)} , Real-Time Ethernet interface ³⁾
	3:	Multi Encoder Interface, CAN ^{® 2)} , Real-Time Ethernet interface ³⁾ , RS485-potential free
	4:	No Encoder, CAN ^{® 2)} , Real-Time Ethernetinterface ³⁾ , safe relay
	5:	Multi Encoder Interface, CAN ^{® 2)} , Real-Time Ethernet interface ³⁾ , safety relay
	B:	Multi Encoder Interface, CAN ^{® 2)} , Real-Time Ethernet interface ³⁾ , alternative connector



continued on the next page

PRODUCT DESCRIPTION

x	x	F	6	x	x	x	-	x	x	x	x	
Switching frequency, Software current limit, Turn-off current											0: 2 kHz / 125% / 150%	8: 2 kHz / 180% / 216%
											1: 4 kHz / 125% / 150%	9: 4 kHz / 180% / 216%
											2: 8 kHz / 125% / 150%	A: 8 kHz / 180% / 216%
											3: 16 kHz / 125% / 150%	B: 8 kHz / HSD
											4: 2 kHz / 150% / 180%	C: 6 kHz / HSD
											5: 4 kHz / 150% / 180%	Non standard switching
											6: 8 kHz / 150% / 180%	D: frequency / Overload characteristic
											7: 16 kHz / 150% / 180%	E: Special Device
Voltage/ Connection type											1: 3ph 230 V AC/DC with braking transistor	
											2: 3ph 230 V AC/DC without braking transistor	
											3: 3ph 400 V AC/DC with braking transistor	
											4: 3ph 400 V AC/DC without braking transistor	
											A: 3ph 400 V AC/DC incl. GTR7 / max. rectifier / max. pre-charging	
											B: 3ph 400 V AC/DC without GTR7 / max. rectifier / max. pre-charging	
											C: 3ph 400 V AC/DC. GTR7-variant 2	
											D: 3ph 400 V AC/DC GTR7-variant 2 / max. rectifier / max. pre-charging	
Housing											2...9	
Equipment											1: Safety module type 1/STO at control type K	
											3: Safety module type 3	
											4: Safety module type 4	
											5: Safety module type 5	
Control type											A: APPLICATION	
											K: COMPACT	
											P: PRO	
Series											COMBIVERT F6	
Inverter size											10...33	

Table 1: Part code

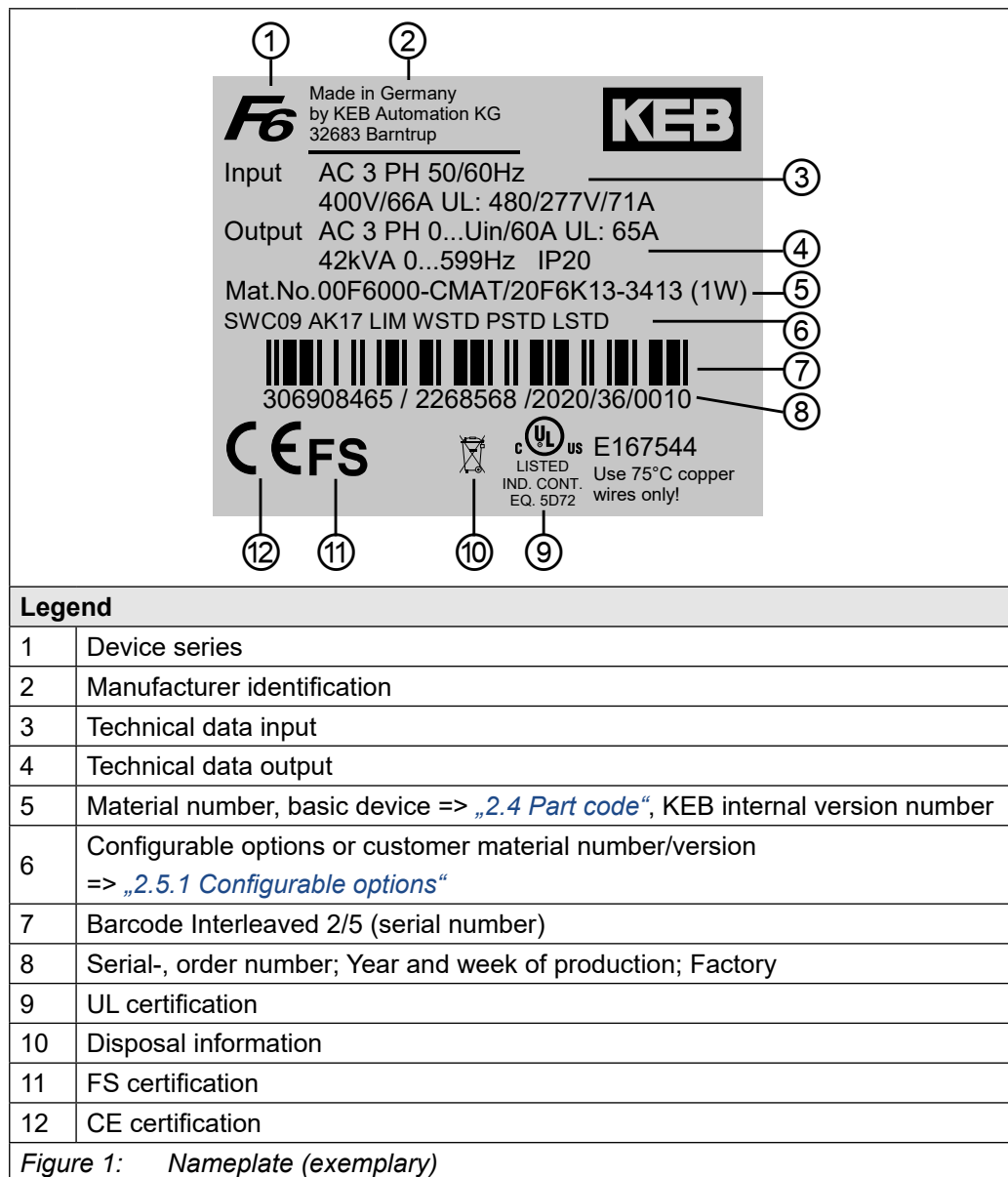
Table 1: Part code

- ¹⁾  EtherCAT® is registered trademark and patented technology, licensed by Beckhoff Automation GmbH, Germany
- ²⁾  CANopen® is registered trademark of CAN in AUTOMATION - International Users and Manufacturers Group e.V.
- ³⁾ The Real-Time Ethernetbusmodul / Real-Time Ethernet interface contains various fieldbus control types which can be adjusted by software (parameter fb68)



The part code may not be used as order code, but only for identification!

2.5 Nameplate



2.5.1 Configurable options

Features	Feature values	Description
Software	SWxxx ¹⁾	Software status of the drive converter
Accessories	Axxx ¹⁾	Selected accessories
	NAK	No accessories
Output frequency activation	LIM	Limitation to 599 Hz
	ULO	> 599 Hz activated
Warranty	WSTD	Warranty - Standard
	Wxxx ¹⁾	Warranty extension
Parameterization	PSTD	Parameterization - Standard
	Pxxx ¹⁾	Parameterization - Customer-specific
Nameplate logo	LSTD	Logo - Standard
	Lxxx ¹⁾	Logo - Customer-specific
<i>Figure 2: Configurable options</i>		

¹⁾ „x“ indicates a variable value

3 Technical data

Unless otherwise indicated, all electrical data in the following chapter refer to a 3-phase AC mains.

3.1 Operating conditions

3.1.1 Climatic environmental conditions

Storage		Standard	Class	Descriptions
Ambient temperature		EN 60721-3-1	1K4	-25...55 °C
Relative humidity		EN 60721-3-1	1K3	5...95 % (without condensation)
Storage height		–	–	Max. 3000 m above sea level
Transport		Standard	Class	Descriptions
Ambient temperature		EN 60721-3-2	2K3	-25...70 °C
Relative humidity		EN 60721-3-2	2K3	95 % at 40 °C (without condensation)
Operation		Standard	Class	Descriptions
Ambient temperature		EN 60721-3-3	3K3	5...40 °C (extended to -10...45 °C)
Coolant inlet temperature	Air	–	–	5...40 °C (extended to -10...45 °C)
	Water	–	–	5...40 °C (device size 28) 5...55 °C (device size 26)
Relative humidity		EN 60721-3-3	3K3	5...85 % (without condensation)
Version and degree of protection		EN 60529	IP20	Protection against foreign material > ø12.5 mm No protection against water Non-conductive pollution, occasional condensation when PDS is out of service. Drive controller generally, except power connections and fan unit (IPxxA)
Site altitude		–	–	Max. 2000 m above sea level • With site altitudes over 1000 m a derating of 1 % per 100 m must be taken into consideration. • With site altitudes over 2000 m, the control board to the mains has only basic isolation. Additional measures must be taken when wiring the control.

Table 2: Climatic environmental conditions

¹⁾ Observe the notes on the coolant -> „6.1.3 Requirements for the coolant“

OPERATING CONDITIONS

3.1.2 Mechanical environmental conditions

Storage	Standard	Class	Descriptions
Vibration limits	EN 60721-3-1	1M2	Vibration amplitude 1.5 mm (2...9 Hz) Acceleration amplitude 5 m/s ² (9...200 Hz)
Shock limit values	EN 60721-3-1	1M2	40 m/s ² ; 22 ms
Transport	Standard	Class	Descriptions
Vibration limits	EN 60721-3-2	2M1	Vibration amplitude 3.5 mm (2...9 Hz) Acceleration amplitude 10 m/s ² (9...200 Hz)
Shock limit values	EN 60721-3-2	2M1	100 m/s ² ; 11 ms
Operation	Standard	Class	Descriptions
Vibration limits	EN 60721-3-3	3M4	Vibration amplitude 3.0 mm (2...9 Hz) Acceleration amplitude 10 m/s ² (9...200 Hz)
	EN 61800-5-1	–	Vibration amplitude 0.075 mm (10...58 Hz) Acceleration amplitude 10 m/s ² (58...150 Hz)
Shock limit values	EN 60721-3-3	3M4	100 m/s ² ; 11 ms
Pressure in the water cooler	–	–	Rated operating pressure: 10 bar Max. operating pressure: 10 bar
Table 3: Mechanical environmental conditions			

3.1.3 Further environmental operating conditions

Operation	Standard	Class	Descriptions
Chemically active substances	EN 60721-3-3	3C2	No salt spray
Mechanically active substances		3S2	–
Organic		3B1	–
UV resistance		–	No requirement
Table 4: Further environmental operating conditions			

3.1.4 Electrical operating conditions

3.1.4.1 Device classification

Requirement	Standard	Class	Descriptions
Overvoltage category	EN 61800-5-1	III	–
Pollution degree	EN 61800-5-1	2	Non-conductive pollution, occasional condensation when PDS is out of operation

Table 5: Device classification

3.1.4.2 Electromagnetic compatibility

For devices without an internal filter, an external filter is required to comply with the following limits.

EMC emitted interference	Standard	Class	Descriptions
Conducted interference emission	EN 61800-3	C2 / C3	The specified value is only maintained in conjunction with a filter. Information on interference suppression (rated switching frequency, max. motor cable length) can be found in the corresponding filter instructions.
Radiated emitted interference	EN 61800-3	C2	–
EMF	EN 61800-5-1	–	Table P.2
Immunity	Standard	Level	Descriptions
Static discharges	EN 61000-4-2	8 kV 4 kV	AD (air discharge) CD (contact discharge)
Burst - Ports for process measurement control lines and signal interfaces	EN 61000-4-4	2 kV	–
Burst - AC - Power ports	EN 61000-4-4	4 kV	–
Surge - Power ports	EN 61000-4-5	1 kV 2 kV	Phase-phase Phase-ground
Conducted immunity, induced by high-frequency fields	EN 61000-4-6	10 V	0.15...80 MHz
Electromagnetic fields	EN 61000-4-3	10 V/m 3 V/m 1 V/m	80 MHz...1 GHz 1.4...2 GHz 2...2.7 GHz
voltage dips	EN 61000-4-11 EN 61000-4-34	Class 3	–
frequency fluctuations	EN 61000-4-28	± 2 %	–
Voltage unbalances	EN 61000-2-4	≤ 3 %	–

Table 6: Electromagnetic compatibility

3.2 Device data of the High Speed Drive devices

3.2.1 Overview of the High Speed Drive devices

The technical data are for 2/4-pole standard motors. For High Speed Drive devices, the drive controller must be dimensioned to the rated motor current.

Device size		26	26 ⁸⁾	27	28 ⁸⁾
Housing		7			
Device type		High Speed Drive			
Rated apparent output power	S_{out} / kVA	173		208	256
Max. rated motor power	¹⁾ P_{mot} / kW	132		160	200
Rated input voltage	U_N / V	400 (UL: 480)			
Input voltage range	U_{in} / V	280...550			
Mains phases		3			
Mains frequency	f_N / Hz	50 / 60 ±2			
Rated input current @ U_N = 400V	I_{in} / A	263		315	390
Rated input current @ U_N = 480V	I_{in_UL} / A	217		269	337
Insulation resistance @ U_{dc} = 500V	R_{iso} / MΩ	> 15			
Output voltage	U_{out} / V	0... U_{in}			
Output frequency	²⁾ f_{out} / Hz	0...599 (0...2000)			
Output phases		3			
Rated output current @ U_N = 400V	I_N / A	250		300	370
Rated output current @ U_N = 480V	I_{N_UL} / A	210		260	325
Rated output overload (60s)	^{3) 4)} I_{60s} / %	106	125	106	106
Software current limit	³⁾ I_{lim} / %	112,5	125	112,5	112,5
Overcurrent	³⁾ I_{OC} / %	135	150	135	135
Rated switching frequency	f_{SN} / kHz	8	8	6	8
Max. switching frequency	⁵⁾ f_{S_max} /kHz	16	16	16	16
Power dissipation at rated operation	¹⁾ P_D / W	3800	3800	4000	6000
Overload current over time	³⁾ I_{OL} / %	„3.2.3.1 Overload characteristic (OL)“			
Maximum current 0Hz/100Hz at f_s =2 kHz	I_{out_max} / %	96 / 135	116 / 150	80 / 135	78 / 135
Maximum current 0Hz/100Hz at f_s =4 kHz	I_{out_max} / %	64 / 135	80 / 150	53 / 135	54 / 125
Maximum current 0Hz/100Hz at f_s =8 kHz	I_{out_max} / %	32 / 125	44 / 150	26 / 90	30 / 125
Maximum current 0Hz/100Hz at f_s =16 kHz	I_{out_max} / %	12 / 48	16 / 48	10 / 40	11 / 32
Max. braking current	I_{B_max} / A	382			
continued on the next page					

Device size	26	26 ⁸⁾	27	28 ⁸⁾
Housing	7			
Device type	High Speed Drive			
Min. braking resistor value R_{B_min} / Ω	2,2			
Braking transistor ⁶⁾	Max. cycle time: 120 s; Max c.d.f.: 50 %			
Protective function for braking transistor	Short-circuit monitoring			
Protective function braking resistor (Error GTR7 always on) ⁷⁾	Feedback signal evaluation and current switch-off (only for AC mains connection)			
Max. motor cable length shielded ⁹⁾ // m	100			

Table 7: Overview of the HSD device data

- ¹⁾ Rated operation corresponds to $U_N = 400V$, rated switching frequency, output frequency = 50Hz (4-pole standard asynchronous motor).
- ²⁾ The output frequency is to be limited in such a way that it does not exceed 1/10 of the switching frequency. Notice! Devices with a maximum output frequency higher than 599Hz are subject to export restrictions.
- ³⁾ The values refer in % to the rated output current I_N .
- ⁴⁾ Observe limitations => „3.2.3.1 Overload characteristic (OL)“.
- ⁵⁾ A detailed description of the Derating => „3.3.1 Switching frequency and temperature“.
- ⁶⁾ The cyclic duration factor is additionally limited by the used braking resistor.
- ⁷⁾ The feedback signal evaluation monitors the functionality of the braking transistor. The power is switched off via the internal mains input bridge of the AC supply. There is no current switch-off with DC power supply.
- ⁸⁾ Only for water cooling.
- ⁹⁾ The maximum cable length depends on various factors. Further information can be found in the corresponding filter instructions.

3.2.2 Voltage and frequencies for 400V devices

Input voltages and frequencies		
Rated input voltage	U_N / V	400
Rated mains voltage (USA)	U_{N_UL} / V	480
Input voltage range	U_{IN} / V	280...550
Input phases		3
Mains frequency	f_N / Hz	50/60
Mains frequency tolerance	f_N / Hz	± 2

Table 8: Input voltages and frequencies of the 400V devices

DC link voltage		
DC link rated voltage @ $U_N = 400V$	U_{N_dc} / V	565
DC link rated voltage @ $U_{N_UL} = 480V$	$U_{N_UL_dc} / V$	680
DC link voltage working voltage range	U_{IN_dc} / V	390...780

Table 9: DC link voltage for 400V devices

Output voltages and frequencies		
Output voltage at AC supply	¹⁾ U_{out} / V	$0 \dots U_{N_ac}$
Output frequency	²⁾ f_{out} / Hz	$0 \dots 599 (0 \dots 2000)$
Output phase		3

Table 10: Output voltages and frequencies of the 400V devices

¹⁾ The voltage to the motor is dependent on the actual input voltage and the control method („3.2.2.1 Example of the calculation of the possible motor voltage:“).

²⁾ The output frequency is to be limited in such a way that it does not exceed 1/10 of the switching frequency. Devices with a maximum output frequency higher than 599Hz are restricted for export.

3.2.2.1 Example of the calculation of the possible motor voltage:

The motor voltage for dimensioning of the drive is depending on the used components.
The motor voltage reduces according to the following table:

Component	Reduction / %	Example
Mains choke U_k	4	Open-loop drive converter with mains- and motor choke at non-rigid supply system: 400 V mains voltage (100%) - 36 V reduced voltage (11 %) = 356 V motor voltage
Drive converter open-loop	4	
Drive converter closed-loop	8	
Motor choke U_k	1	
Non-rigid supply system	2	

Table 11: Example of the calculation of the possible motor voltage:

3.2.3 Input and output currents / overload

Device size		26	26 ⁴⁾	27	28 ⁴⁾
Rated input current @ $U_N = 400V$	¹⁾ I_{in} / A	263	263	315	390
Rated input current @ $U_{N_UL} = 480V$	¹⁾ I_{in_UL} / A	217	217	269	337
Rated input current DC @ $U_{N_dc} = 565V$	I_{in_dc} / A	317	317	380	469
Rated input current DC @ $U_{N_UL_dc} = 680V$	$I_{in_UL_dc} / A$	266	266	330	412
Rated output current @ $U_N = 400V$	I_N / A	250	2520	300	370
Rated output current @ $U_{N_UL} = 480V$	I_{N_UL} / A	210	210	260	325
Rated output overload (60s)	²⁾ $I_{60s} / \%$	106	125	106	106
Overload current	²⁾ $I_{OL} / \%$	„3.2.3.1 Overload characteristic (OL)“			
Software current limit	^{2) 3)} $I_{lim} / \%$	112,5	125	112,5	112,5
Overcurrent	²⁾ $I_{oc} / \%$	135	150	135	135

Table 12: Input and output currents and overload of the HSD devices

¹⁾ The values resulting from rated operation with B6 rectifier circuit and mains choke 4% U_k .

²⁾ The values refer in % to the rated output current I_N .

³⁾ Limitation of the current setpoint in closed-loop operation. This setpoint limit is not active in v/f operation.

⁴⁾ Only for water cooling.

3.2.3.1 Overload characteristic (OL)

All drive controllers can be operated at rated switching frequency with an utilisation of 106% or 125% for 60s.

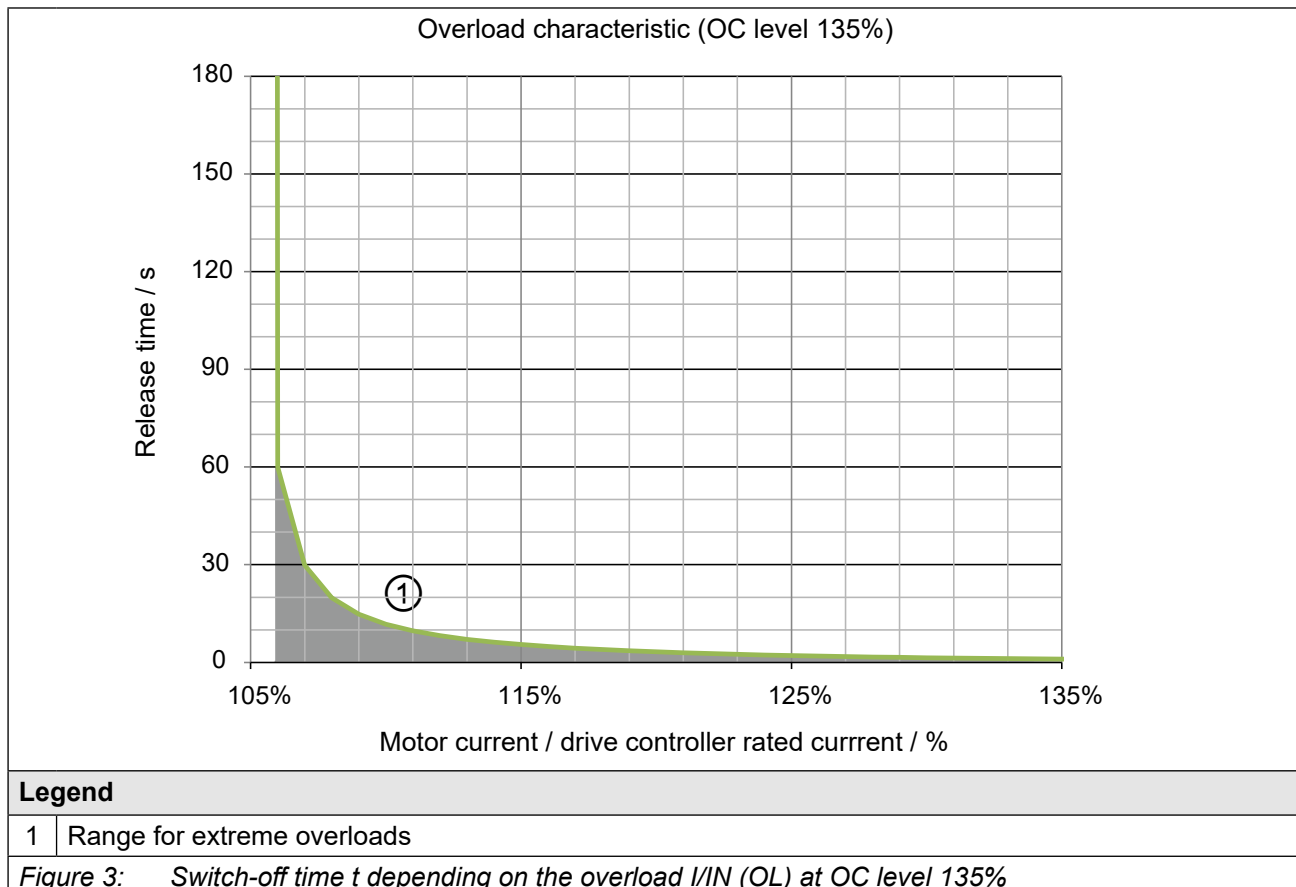
The OL overload function is a root mean square (RMS) function.

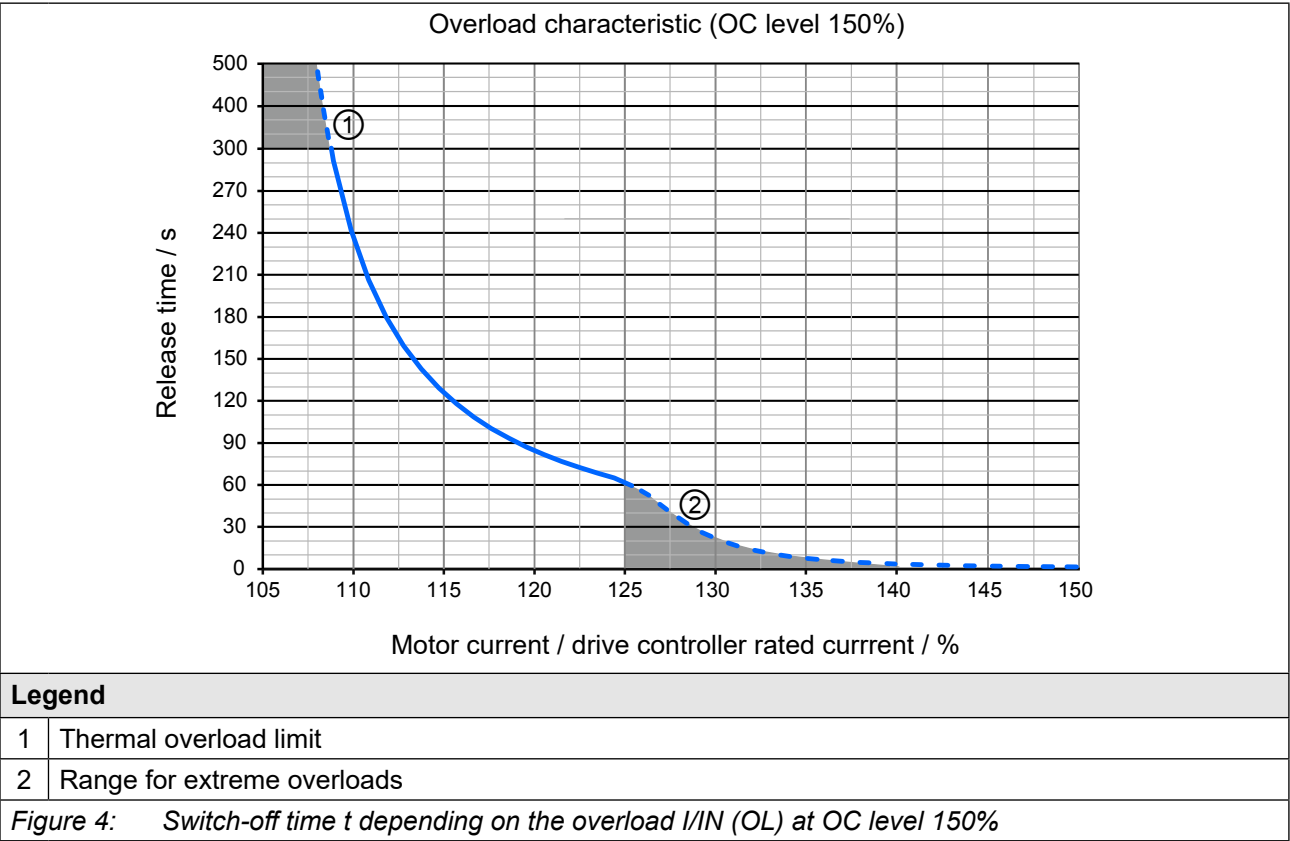
The greater the difference between the overload and underload phases, the greater the deviation of the RMS from the arithmetic mean value.

For extreme overloads (\Rightarrow „Figure 3: Switch-off time t depending on the overload I/I_N (OL) at OC level 135%“) the load is weighted more heavily. This means the load is provided with a factor for the calculation of the RMS value, by way that the overload protection function triggers, even if the RMS value does not reach 100%.

Restrictions:

- The thermal design of the heat sink is based on the rated operation. The following values are taken into account: Rated output current, ambient temperature, rated switching frequency, rated voltage.
- At high ambient temperatures and/or high heat sink temperatures (for example, by preceding utilisation nearby 100%) the drive controller can change to overtemperature error before triggering the protective function OL.
- At low output frequencies or switching frequencies higher than the rated switching frequency, the frequency-dependent maximum current can be exceeded before triggering the overload error OL and error OL2 can be triggered
 \Rightarrow „3.2.3.2 Frequency-dependent maximum current (OL2)“.





- On exceeding a load of 105 % the overload integrator starts.
- When falling below the integrator counts backwards.
- If the integrator reaches the overload characteristic "Error! overload (OL)" is triggered.

After a cooling down period, the integrator can be reset now. The drive controller must remain switched on during the cooling down phase.

Operation in the range of the thermal overload limit

Due to the high slope of the overload characteristic, the duration of a permissible overload in range ① cannot be determined exactly. Therefore, the design of the drive controller should be assumed to have a maximum overload time of 300s.

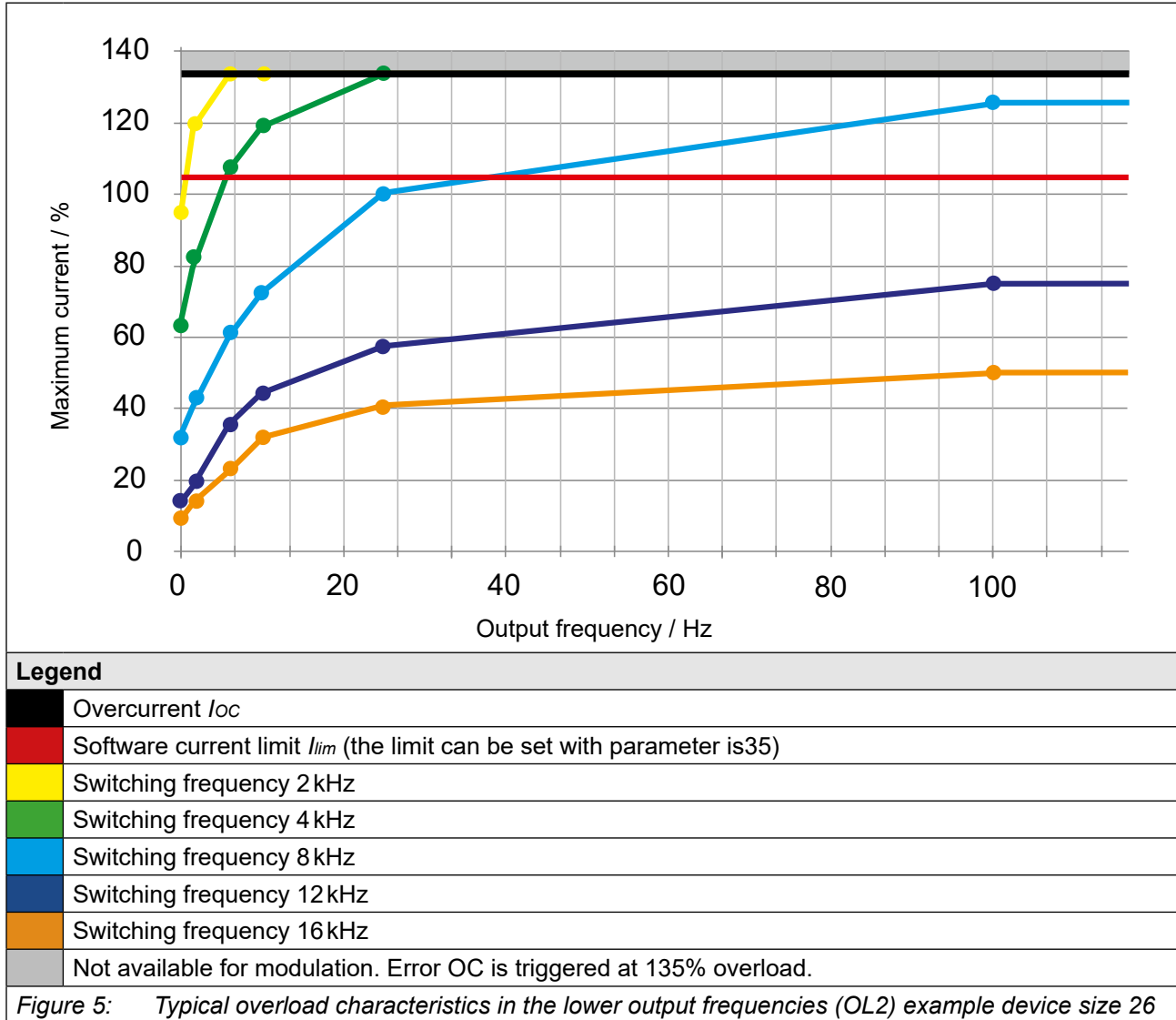
3.2.3.2 Frequency-dependent maximum current (OL2)

The characteristics of the maximum currents for a switching frequency which are depending on the output frequency are different for each drive controller, but in general the following rule applies to housing 7:

- Lower maximum currents apply for switching frequencies > rated switching frequency.

If error (OL2) shall be triggered on exceeding the maximum currents or if the switching frequency is automatically reduced (derating) can be adjusted in the drive controller parameters.

The following characteristic curve indicates the permissible maximum current for the output frequency values 0 Hz, 1.5 Hz, 6 Hz, 10 Hz, 25 Hz and 100 Hz. Device size 26 (air-cooled) is represented exemplary.



The frequency-dependent maximum current I_{out_max} refers in % to the rated output current I_N .

The current remains constant from the last specified output frequency value.



The values for the respective device size are listed in the following tables.

Frequency-dependent maximum current (air cooler)

Device size		26					
Rated switching frequency		8 kHz					
Output frequency	f_{out} / Hz	0	1,5	6	10	25	100
Frequency-dependent maximum current @ f_s I_{out_max} / % <i>Basic Time Period = 62.5 μs (Parameter is22=0)</i>	2 kHz	96	120	135	135	135	135
	4 kHz	64	80	108	120	135	135
	8 kHz	32	40	60	72	100	125
	16 kHz	12	16	24	32	40	48
Frequency-dependent maximum current @ f_s I_{out_max} / % <i>Basic Time Period = 71.4 μs (Parameter is22=1)</i>	1.75 kHz	96	120	135	135	135	135
	3.5 kHz	72	90	119	132	135	135
	7 kHz	40	50	72	84	113	135
	14 kHz	14	18	30	38	48	60
Frequency-dependent maximum current @ f_s I_{out_max} / % <i>Basic Time Period = 83.3 μs (Parameter is22=2)</i>	1.5 kHz	96	120	135	135	135	135
	3 kHz	80	100	129	135	135	135
	6 kHz	48	60	84	96	125	135
	12 kHz	16	20	36	44	56	72
Frequency-dependent maximum current @ f_s I_{out_max} / % <i>Basic Time Period = 100 μs (Parameter is22=3)</i>	1.25 kHz	96	120	135	135	135	135
	2.5 kHz	88	110	135	135	135	135
	5 kHz	56	70	96	108	135	135
	10 kHz	24	30	48	58	78	99

Table 13: Frequency-dependent maximum current for device size 26 (air cooler)

Device size		27					
Rated switching frequency		6 kHz					
Output frequency	f_{out} / Hz	0	1,5	6	10	25	100
Frequency-dependent maximum current @ f_s $I_{out_max}/\%$ <i>Basic Time Period = 62.5 μs (Parameter is22=0)</i>	2 kHz	80	100	125	135	135	135
	4 kHz	53	67	90	100	125	135
	8 kHz	26	33	50	60	75	90
	16 kHz	10	13	20	27	33	40
Frequency-dependent maximum current @ f_s $I_{out_max}/\%$ <i>Basic Time Period = 71.4 μs (Parameter is22=1)</i>	1.75 kHz	80	100	125	135	135	135
	3.5 kHz	60	75	99	110	135	135
	7 kHz	33	42	60	70	88	108
	14 kHz	12	15	25	32	40	50
Frequency-dependent maximum current @ f_s $I_{out_max}/\%$ <i>Basic Time Period = 83.3 μs (Parameter is22=2)</i>	1.5 kHz	80	100	125	135	135	135
	3 kHz	67	83	108	120	135	135
	6 kHz	40	50	70	80	100	125
	12 kHz	13	17	30	37	47	60
Frequency-dependent maximum current @ f_s $I_{out_max}/\%$ <i>Basic Time Period = 100 μs (Parameter is22=3)</i>	1.25 kHz	80	100	125	135	135	135
	2.5 kHz	73	92	116	130	135	135
	5 kHz	47	58	80	90	113	135
	10 kHz	20	25	40	48	60	75

Table 14: Frequency-dependent maximum current for device size 27 (air cooler)

Frequency-dependent maximum current (fluid cooler water)

Device size		26					
Rated switching frequency		8 kHz					
Output frequency	f_{out} / Hz	0	1,5	6	10	25	100
Frequency-dependent maximum current @ f_s $I_{out_max}/\%$ <i>Basic Time Period = 62.5 μs (Parameter is22=0)</i>	2 kHz	116	136	150	150	150	150
	4 kHz	80	96	132	144	150	150
	8 kHz	44	52	84	94	136	150
	16 kHz	16	20	26	32	40	48
Frequency-dependent maximum current @ f_s $I_{out_max}/\%$ <i>Basic Time Period = 71.4 μs (Parameter is22=1)</i>	1.75 kHz	116	136	150	150	150	150
	3.5 kHz	89	106	137	146	150	150
	7 kHz	53	63	96	107	140	150
	14 kHz	21	26	34	41	50	60
Frequency-dependent maximum current @ f_s $I_{out_max}/\%$ <i>Basic Time Period = 83.3 μs (Parameter is22=2)</i>	1.5 kHz	116	136	150	150	150	150
	3 kHz	98	116	141	147	150	150
	6 kHz	62	74	108	119	143	150
	12 kHz	26	32	42	50	60	72
Frequency-dependent maximum current @ f_s $I_{out_max}/\%$ <i>Basic Time Period = 100 μs (Parameter is22=3)</i>	1.25 kHz	116	136	150	150	150	150
	2.5 kHz	107	126	146	149	150	150
	5 kHz	71	85	120	132	147	150
	10 kHz	35	42	63	72	98	111

Table 15: Frequency-dependent maximum current for device size 26 (water cooler)

Device size		28					
Rated switching frequency		8 kHz					
Output frequency	f_{out} / Hz	0	1,5	6	10	25	100
Frequency-dependent maximum current @ f_s <i>Basic Time Period = 62.5 μs (Parameter is22=0)</i>	2 kHz	78	92	130	135	135	135
	4 kHz	54	65	89	97	114	125
	8 kHz	30	35	57	64	92	125
	16 kHz	11	14	18	22	27	32
Frequency-dependent maximum current @ f_s <i>Basic Time Period = 71.4 μs (Parameter is22=1)</i>	1.75 kHz	78	92	130	135	135	135
	3.5 kHz	60	72	99	108	124	134
	7 kHz	36	43	65	72	97	125
	14 kHz	14	18	23	28	34	41
Frequency-dependent maximum current @ f_s <i>Basic Time Period = 83.3 μs (Parameter is22=2)</i>	1.5 kHz	78	92	130	135	135	135
	3 kHz	66	78	110	119	135	135
	6 kHz	42	50	73	80	103	125
	12 kHz	18	22	28	34	41	49
Frequency-dependent maximum current @ f_s <i>Basic Time Period = 100 μs (Parameter is22=3)</i>	1.25 kHz	78	92	130	135	135	135
	2.5 kHz	72	75	120	130	135	135
	5 kHz	48	57	81	89	108	125
	10 kHz	24	28	43	49	66	87

Table 16: Frequency-dependent maximum current for device size 28 (water cooler)

3.2.4 Overview of rectifier data for HSD devices

Device size		26	27	28
Rectifier rated power	P_{rect} / kW	144	174	217
Rectifier continuous power	¹⁾ $P_{rect_cont} / \text{kW}$	217	217	217
Continuous input current @ $U_N = 400 \text{ V}$	¹⁾ I_{in_cont} / A	390	390	390
Continuous input current @ $U_{N_UL} = 480 \text{ V}$	¹⁾ $I_{in_UL_cont} / \text{A}$	337	337	337
Rated output current DC @ $U_{N_dc} = 565 \text{ V}$	I_{out_dc} / A	317	380	469
Continuous output current DC @ $U_{N_dc} = 565 \text{ V}$	¹⁾ $I_{out_dc_cont} / \text{A}$	469	469	469
Rated output current DC @ $U_{N_UL_dc} = 680 \text{ V}$	$I_{out_UL_dc} / \text{A}$	266	330	412
Continuous output current DC @ $U_{N_UL_dc} = 680 \text{ V}$	¹⁾ $I_{out_UL_dc_cont} / \text{A}$	412	412	412

Table 17: Overview of rectifier data for HSD devices

¹⁾ Continuous operation is a load that exceeds the rated operation. Continuous operation only occurs if the internal rectifier is used to supply additional drive controllers via the DC terminals => „5.3.6 DC-bus connection“. In continuous operation, the OH error can be triggered depending on the operating conditions of the internal inverter.

3.2.5 Power dissipation at rated operation

Device size		26	26 ³⁾	27	28 ³⁾
Rated switching frequency	f_{SN} / kHz	8	8	6	8
Power dissipation at rated operation	¹⁾ P_D / W	4460	3390	4700	5450
Power dissipation at rated operation DC	²⁾ P_{D_dc} / W	4140	3070	4260	4800

Table 18: Power dissipation of the HSD devices

¹⁾ Rated operation corresponds to $U_N = 400 \text{ V}$; f_{SN} ; I_N ; $f_N = 50 \text{ Hz}$ (typically value)

²⁾ Rated operation DC corresponds to $U_{N_dc} = 565 \text{ V}$; I_N (typical value)

³⁾ Only available as fluid cooler (water)

3.2.6 Protection for HSD devices

3.2.6.1 Fuse protection for AC supply

Device size	Max. size of the fuse / A				
	$U_N = 400V$ gG (IEC)	$U_N = 480V$ class „J“	$U_N = 480V$ class „J“	$U_N = 480V$	
	SCCR 30 kA	SCCR 10 kA	SCCR 18 kA	SCCR 100 kA	Type
26	315	300	---	315	SIBA 206xy32.315
					COOPER BUSSMANN 170M4xy0
					LITTELFUSE PSR030yy0315
27	355	350	---	350	SIBA 206xy32.350
					COOPER BUSSMANN 170M4xy1
					LITTELFUSE PSR030yy0350
28	400	---	450	450	SIBA 206xy32.450
					COOPER BUSSMANN 170M4xy3
					LITTELFUSE PSR030yy0450

Table 19: AC fuses of the HSD devices

¹⁾ "x" stands for various indicators. "y" stands for different connection variants.



Short-circuit capacity

According to the requirements of EN 61439-1 and EN 61800-5-1, the following applies to connection to a power supply: The devices are suitable for use in a circuit capable of delivering not more than 30 kA eff. unaffected symmetrical short-circuit current.

3.2.6.2 Protecting HSD devices with DC power supply

Device size	Recommended size of the fuse / A		Permissible fuses ¹⁾
	$U_{N_dc} = 565V$	$U_{N_UL_dc} = 680V$	
	SCCR 85 kA	SCCR 85 kA	
26	400	350	SIBA 20 568 34.400 ²⁾ Bussmann 170M4246 Bussmann 170M6245 Littelfuse PSR073DL0700
27	500	400	
28	630	500	

Table 20: DC fuses for HSD devices

¹⁾ Fuses of the same type with lower rated currents can be used if they are suitable for the application.

²⁾ Fuse without UL certification.

NOTICE

Observe the rated voltage of the fuse!

- The rated voltage of the fuse must be at least equal to the maximum DC supply voltage of the drive controller.

3.3 General electrical data

3.3.1 Switching frequency and temperature

The drive controller cooling is designed by way that the heat sink overtemperature threshold is not exceeded at rated conditions. A switching frequency higher than the rated switching frequency also produces higher losses and thus a higher heat sink heating. If the heat sink temperature reaches a critical threshold (T_{DR}), the switching frequency can be reduced automatically step by step. This prevents that the drive controller switches off due to overheating of the heat sink. If the heat sink temperature falls below the threshold T_{UR} , the switching frequency is increased back to the setpoint. At temperature T_{EM} the switching frequency is immediately reduced to rated switching frequency. „Derating“ must be activated, for this function to work.

3.3.1.1 Switching frequencies and temperatures for air coolers

Device size		26	27
Rated switching frequency	¹⁾ f_{SN} / kHz	8	6
Max. switching frequency	¹⁾ f_{S_max} / kHz	16	16
Min. switching frequency	¹⁾ f_{S_min} / kHz	1,25	1,25
Max. heat sink temperature 1	T_{HS1} / °C	90	92
Max. heat sink temperature 2	T_{HS2} / °C	77	82
Max. heat sink temperature 3	T_{HS3} / °C	82	84
Max. interior temperature power unit 1	T_{ID_PU1} / °C	65	65
Max. interior temperature power unit 2	T_{ID_PU2} / °C	75	75
Max. interior temperature power unit 3	T_{ID_PU3} / °C	90	90
Temperature for derating the switching frequency	²⁾ T_{DR} / °C	80	82
Temperature for uprating the switching frequency	²⁾ T_{UR} / °C	70	42
Temperature for switching to rated switching frequency	²⁾ T_{EM} / °C	85	87

Table 21: Switching frequency and temperature of the HSD devices (air cooler)

¹⁾ The output frequency is to be limited in such a way that it does not exceed 1/10 of the switching frequency.

²⁾ The switching point refers to the temperature of T_{HS1}

3.3.1.2 Switching frequencies and temperatures for fluid coolers (water)

Device size		26	28
Rated switching frequency	¹⁾ f_{SN} / kHz	8	8
Max. switching frequency	¹⁾ f_{S_max} / kHz	16	16
Min. switching frequency	¹⁾ f_{S_min} / kHz	1,25	1,25
Max. heat sink temperature 1	T_{HS1} / °C	77	72
Max. heat sink temperature 2	T_{HS2} / °C	72	64
Max. heat sink temperature 3	T_{HS3} / °C	72	64
Max. interior temperature power unit 1	T_{ID_PU1} / °C	65	65
Max. interior temperature power unit 2	T_{ID_PU2} / °C	75	75
Max. interior temperature power unit 3	T_{ID_PU3} / °C	90	90
Temperature for derating the switching frequency	²⁾ T_{DR} / °C	69	61
Temperature for uprating the switching frequency	²⁾ T_{UR} / °C	64	56
Temperature for switching to rated switching frequency	²⁾ T_{EM} / °C	71	63

Table 22: Switching frequency and temperature of the HSD devices (water cooler)

¹⁾ The output frequency is to be limited in such a way that it does not exceed 1/10 of the switching frequency.

²⁾ The switching point refers to the temperature of T_{HS1}

3.3.2 DC link / braking transistor function



Activation of the braking transistor function

To be able to use the braking transistor, the function must be activated with parameter "is30 braking transistor function".

For more information => [F6 Programming manual](#).

NOTICE

Falling below the minimum braking resistor value!

Destruction of the drive controller

- The minimum brake resistance value must not fall below!

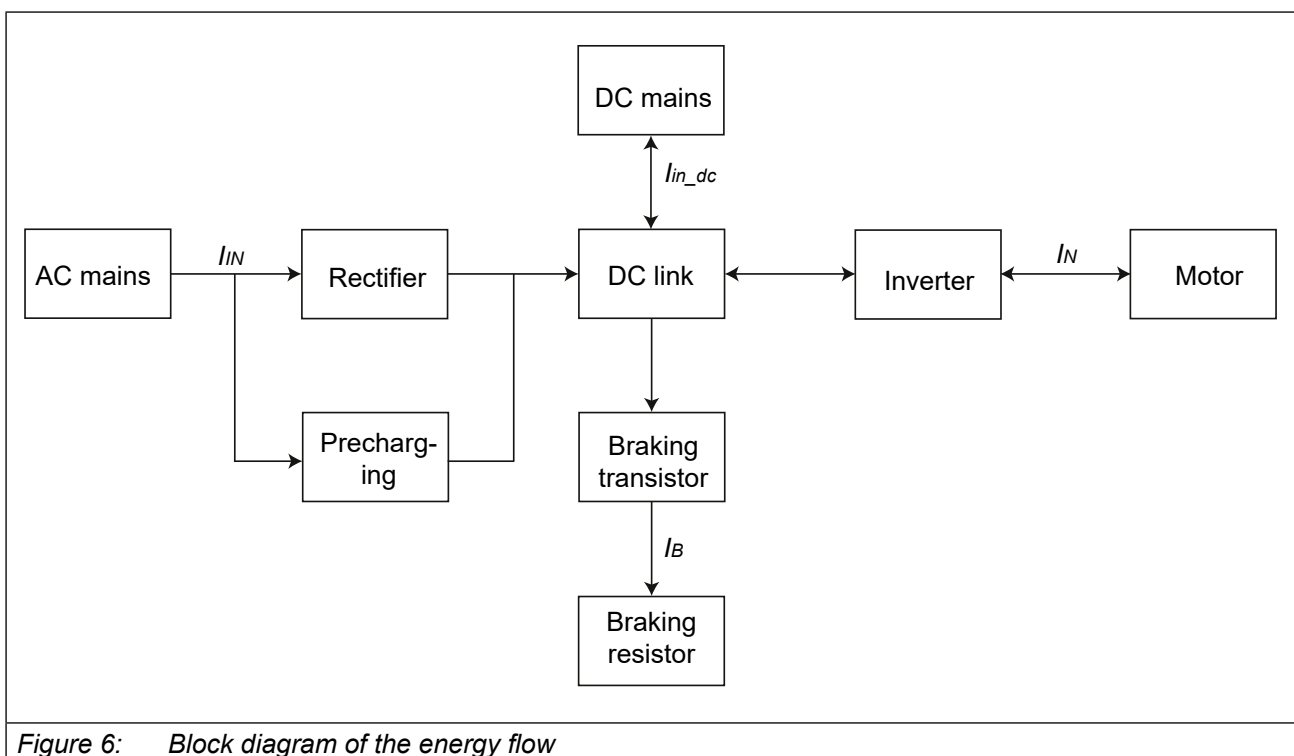


Figure 6: Block diagram of the energy flow

NOTICE

Destruction of the drive controller!

If the error "ERROR GTR7 always ON" occurs, the current consumption is switched off internally via the mains input bridge of the AC supply.

- If the error "ERROR GTR7 always ON" occurs, the drive controller is defective and must be disconnected from the power supply no later than 16 hours!
- With DC mains connection and the use of non-intrinsically safe braking resistors or sub-mounted braking resistors, the drive converter must be de-energised after 1 second at the latest.

GENERAL ELECTRICAL DATA

3.3.2.1 DC link / braking transistor function

Device size		26	27	28
Rated DC link voltage @ $U_N = 400V$	U_{N_dc} / V	565		
Rated DC link voltage @ $U_{N_UL} = 480V$	$U_{N_dc_UL} / V$	680		
DC link voltage working voltage range	U_{in_dc} / V	390...780		
DC switch-off level "ERROR underpotential"	U_{UP} / V	240		
DC switch-off level "ERROR overpotential"	U_{OP} / V	840		
DC switch-off level braking resistor ¹⁾	U_B / V	780		
Max. braking current	I_{B_max} / A	382		
Min. braking resistor value	R_{B_min} / Ω	2,2		
Braking transistor ²⁾		Max. cycle time: 120 s; Max c.d.f.: 50 %		
Protective function for braking transistor		Short-circuit monitoring		
Protective function braking resistor (Error GTR7 always on) ³⁾		Feedback signal evaluation and current switch-off (only for AC mains connection)		
DC link capacity	$C_{int} / \mu F$	7800	10400	12400
Max. prechargeable total capacity @ $U_N = 400V$	$C_{pc_max} / \mu F$	34200	34200	34200
Max. prechargeable total capacity @ $U_{N_UL} = 480V$	$C_{pc_max_UL} / \mu F$	23700	23700	23700

Table 23: DC link / braking transistor function of the HSD devices

- ¹⁾ The DC switching level for the braking transistor is adjustable. The default value is the value specified in the table.
- ²⁾ The cyclic duration factor is additionally limited by the used braking resistor.
- ³⁾ The feedback signal evaluation monitors the functionality of the braking transistor. The power is switched off via the internal mains input bridge of the AC supply. There is no current switch-off with DC power supply.

3.3.3 Thermal continuous current

Device size	26								
Rated switching frequency f_{SN} / kHz	8								
Switching frequency f_S / kHz	2	4	6	8	10	12	14	16	
Thermal continuous current @ $U_N = 400V$ I_{Tout_max} / A	250	250	250	250	210	170	140	115	
Thermal continuous current @ $U_N = 480V$ $I_{Tout_max_UL}$ / A	250	250	250	210	170	135	105	85	

Table 24: Thermal continuous current for device size 26 air cooler

Device size	26								
Rated switching frequency f_{SN} / kHz	8								
Switching frequency f_S / kHz	2	4	6	8	10	12	14	16	
Thermal continuous current @ $U_N = 400V$ I_{Tout_max} / A	250	250	250	250	210	170	140	115	
Thermal continuous current @ $U_N = 480V$ $I_{Tout_max_UL}$ / A	210	210	210	210	170	135	105	85	

Table 25: Thermal continuous current for device size 26 fluid cooler (water)

Device size	27								
Rated switching frequency f_{SN} / kHz	6								
Switching frequency f_S / kHz	2	4	6	8	10	12	14	16	
Thermal continuous current @ $U_N = 400V$ I_{Tout_max} / A	300	300	300	250	210	170	140	115	
Thermal continuous current @ $U_N = 480V$ $I_{Tout_max_UL}$ / A	300	300	250	210	170	135	105	85	

Table 26: Thermal continuous current for device size 27 air cooler

Device size	28								
Rated switching frequency f_{SN} / kHz	8								
Switching frequency f_S / kHz	2	4	6	8	10	12	14	16	
Thermal continuous current @ $U_N = 400V$ I_{Tout_max} / A	370	370	370	370	280	235	185	155	
Thermal continuous current @ $U_N = 480V$ $I_{Tout_max_UL}$ / A	325	325	325	325	230	185	150	125	

Table 27: Thermal continuous current for device size 28 fluid cooler (water)

3.3.4 Fan

Device size		26	26 ¹⁾	27	28 ¹⁾
Interior fan	Number	2	2	2	2
	Speed-variable	yes	yes	yes	yes
Heat sink fan ²⁾	Number	2	-	2	-
	Speed-variable	yes	-	yes	-

Table 28: Fan

¹⁾ Only for water cooling.

¹⁾ Observe external heat sink fan supply => „5.3.7 External heat sink fan supply (FAN)“



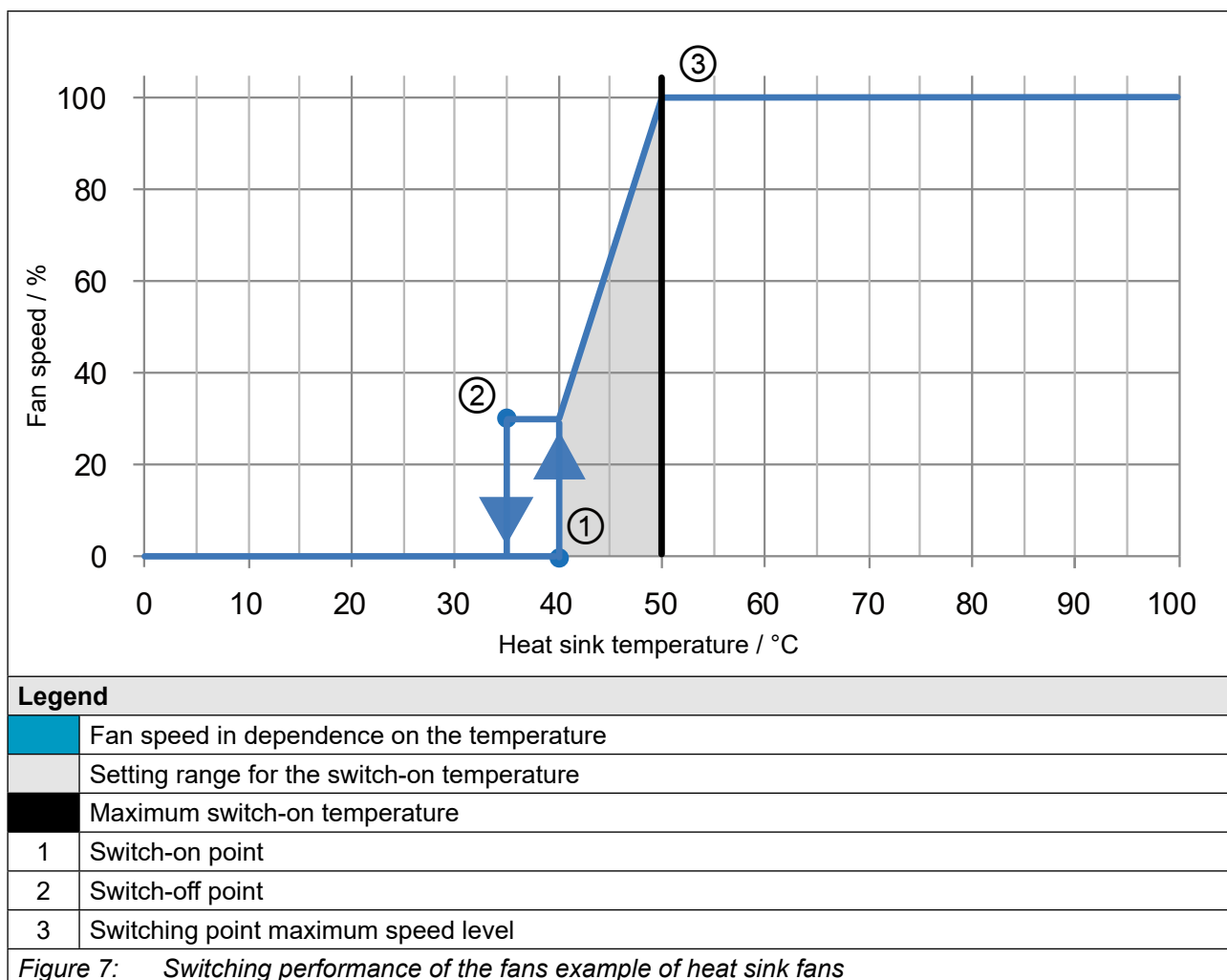
The fans are speed-variable. They are automatically controlled to high or low speed depending on the setting of the temperature limits in the software.

NOTICE
Destruction of the fan!

- Take care that no foreign substances drop into the fan!

3.3.4.1 Switching behaviour of the fans

The temperature monitoring controls the fans with different switch-on and switch-off points.



3.3.4.2 Switching points of the fans

The switching point for the switch-on temperature and the maximum speed level of the fans are adjustable. The following table shows the default values.

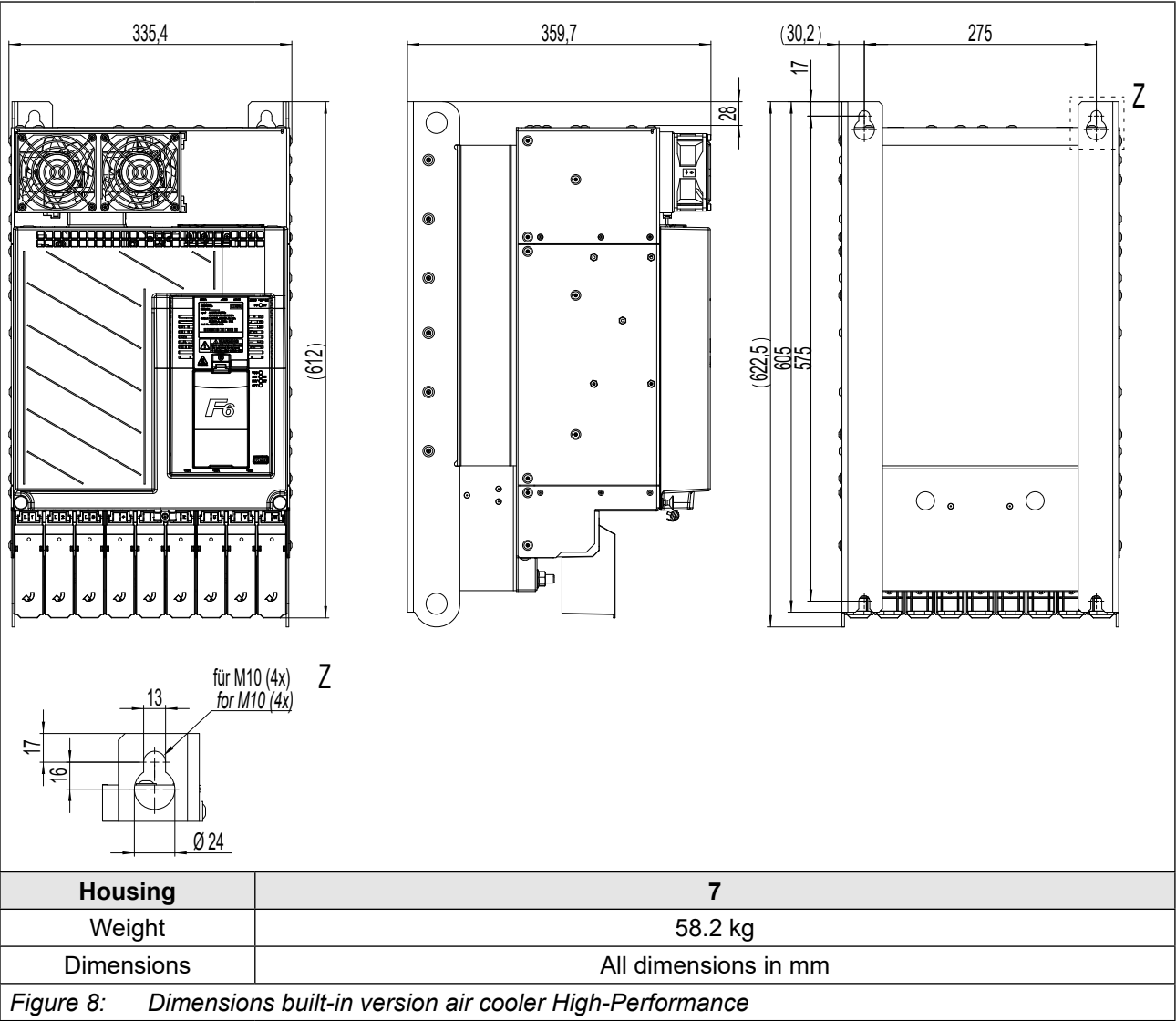
Fan		Heat sink	Interior
Switch-on temperature	$T / ^\circ\text{C}$	40	30
Maximum speed level	$T / ^\circ\text{C}$	50	45

Table 29: Switching points of the fans

4 Installation

4.1 Dimensions and weights

4.1.1 Built-in version air cooler High-Performance



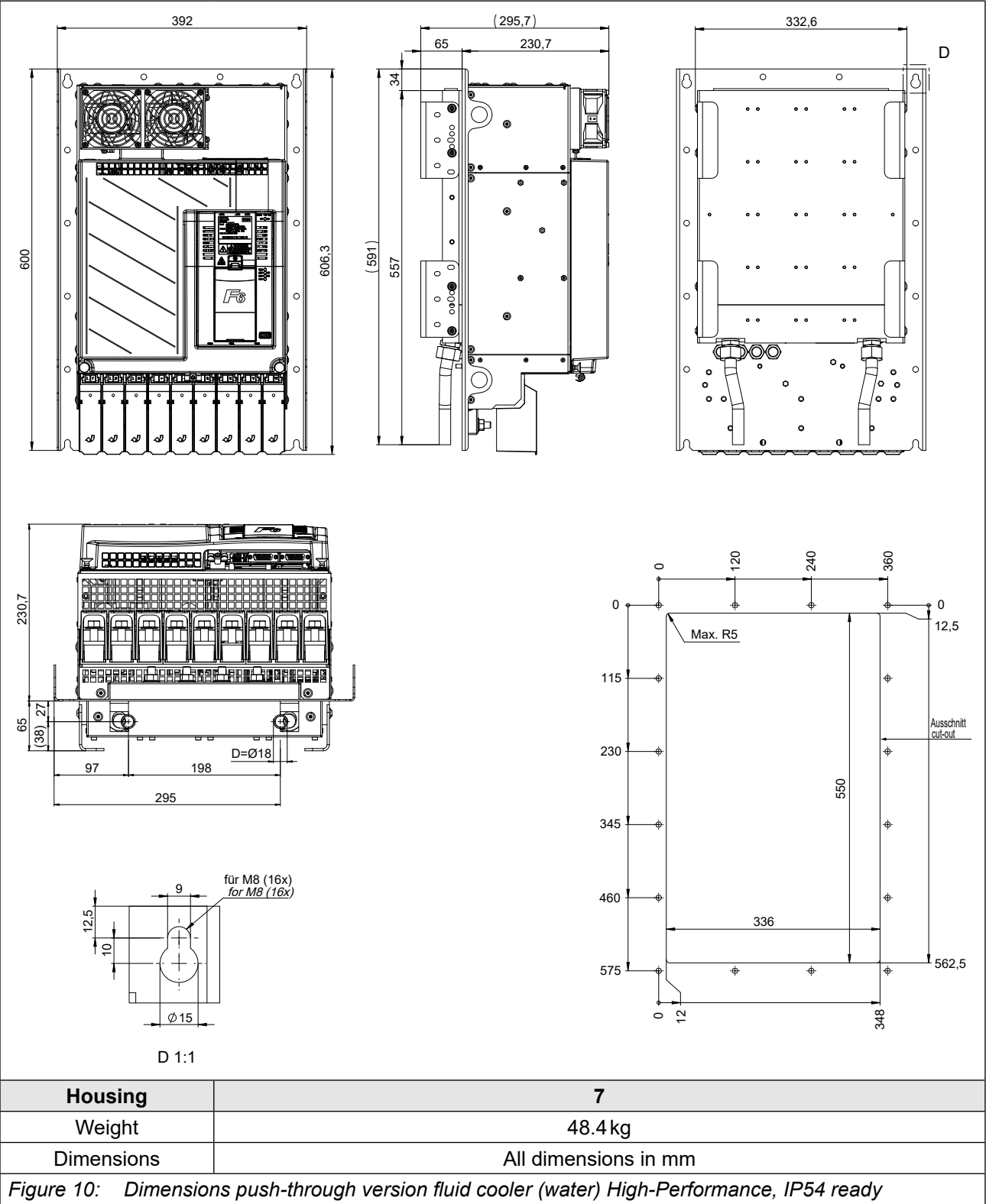
Technical drawing of the push-through version Fluid cooler (water) High-performance. The drawing includes four views: a front view showing two fans and a control panel, a side view showing the unit's profile, a top view showing the internal layout, and a detail view of the mounting bracket. Dimensions are provided in millimeters. The front view shows a width of 335.4 mm and a height of 610.8 mm. The side view shows a depth of 285 mm and a height of 605 mm. The top view shows a width of 275 mm and a height of 575 mm. The detail view shows a mounting bracket with dimensions 13 mm, 16 mm, 17 mm, and a hole diameter of 24 mm. The mounting bracket is labeled "für M10 (4x)" and "for M10 (4x)". The drawing is labeled "Z (1 : 2)".

Housing	7
Weight	45.5 kg
Dimensions	All dimensions in mm

Figure 9: Push-through version Fluid cooler (water) High-performance

DIMENSIONS AND WEIGHTS

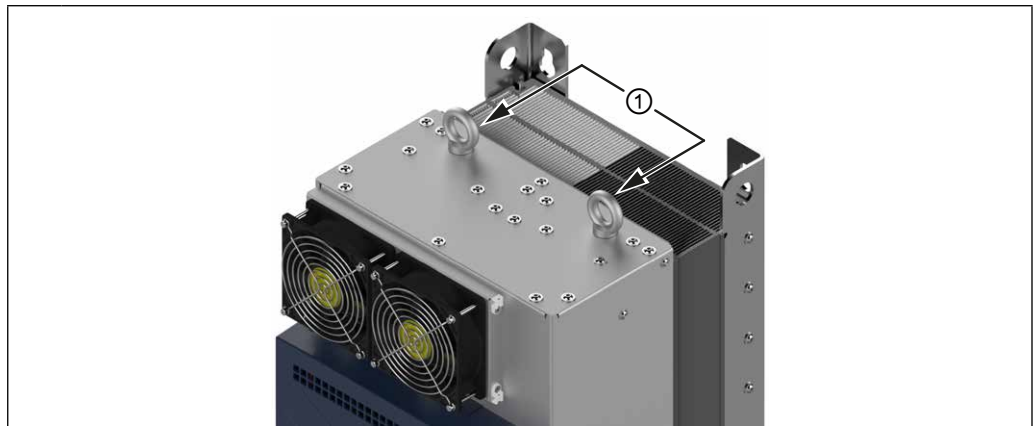
4.1.3 Push-through version fluid cooler (water) High-Performance, IP54 ready



4.2 Control cabinet installation

4.2.1 Control cabinet installation

Drive controllers in housings 7, 8 and 9 have 2 threaded bushes for M10 ring bolts according to *DIN 580* on the top. These are used to accommodate appropriate lifting devices for transport.



Legend

1	M10 ring bolts
---	----------------

Figure 11: Example of an F6 in housing 8 with M10 ring bolts

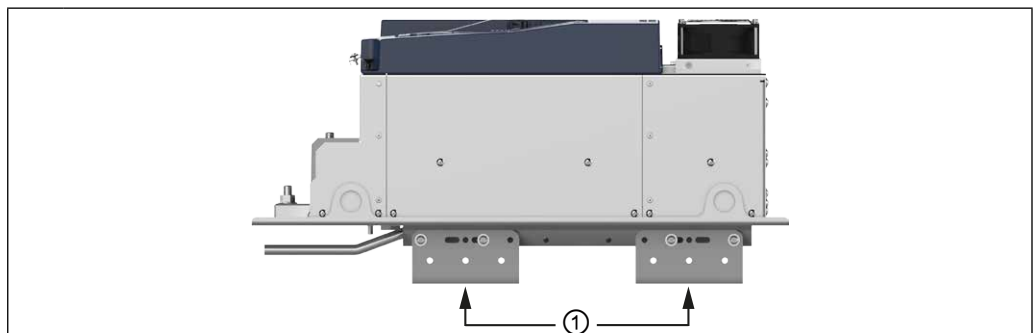
4.2.2 Devices with transport bracket

The transport bracket can be removed after mounting the drive converter. The transport brackets must be stored to make the drive converter transportable again in case of service.

NOTICE

Damage caused by improper mounting

- The transport brackets must not be used to fasten the drive converter!



Legend

1	Transport bracket
---	-------------------

Figure 12: Example of an F6 housing 7 with transport brackets

NOTICE

Damage to the water connections

Bending of the tubes!

- Never set the device down or transport it without the transport brackets!

4.2.3 Mounting instructions

For the mounting of the drive controllers the following mounting materials with the appropriate quality were tested by KEB.

Required material	Tightening torque
Hexagon head screw <i>ISO 4017</i> - M10 - 8.8	50 Nm 442 lb inch
Flat washer <i>ISO 7090</i> - 10 - 200 HV	—
<i>Table 30: Mounting instructions for built-in version</i>	

Required material	Tightening torque
Hexagon head screw <i>ISO 4017</i> - M8 - 8.8	50 Nm 442 lb inch
Flat washer <i>ISO 7090</i> - 8 - 200 HV	—
<i>Table 31: Mounting instructions for push-through version</i>	

NOTICE

Use of other fixing material

- The alternatively selected fixing material must meet the above material characteristics (quality) and tightening torques!

The use of other fixing materials is beyond the control of KEB and is therefore the sole responsibility of the customer.

4.2.4 Mounting distances

Power loss for the control cabinet dimension „3.2.5 Power dissipation at rated operation“. A lower value can be used here depending on the operating mode/load.



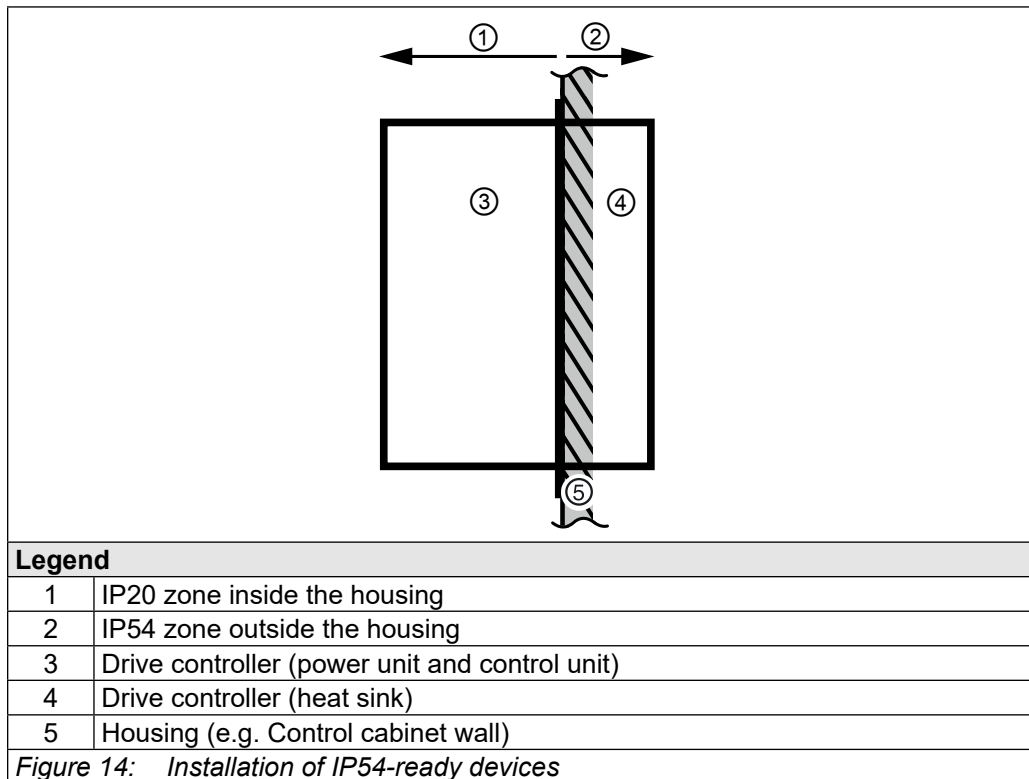
Assembly of the drive controller

For reliable operation, the drive controller must be mounted without any distance on a smooth, closed, metallically bright mounting plate.

Mounting distances	Dimension	Distance in mm	Distance in inch
	A	150	6
	B	100	4
	C	30	1,2
	D	0	0
	E	0	0
	F ¹⁾	50	2
	¹⁾ Distance to preceding elements in the control cabinet door.		

Figure 13: Mounting distances

4.2.5 Installation of IP54-ready devices



IP54 zone: Heat sink outside the housing

The protection class IP54 can only be achieved when the device is properly installed.

For proper installation, a suitable IP54 seal
(=> „5.4.2 Seal for IP54-ready devices“) must be installed between heat sink and housing (e.g. control cabinet wall).

The tightness must be checked after the installation. If properly installed, the separation to the housing corresponds to degree of protection IP54.

In the case of fan-cooled units, the fans must be protected from negative environmental influences.

These include combustible, oily or dangerous fumes or gases, corrosive chemicals, coarse foreign bodies and excessive dust. This applies especially to the access of the heatsink from the top (air outlet). Icing is inadmissible.

UL: Device heat sink is classified as NEMA type 1

IP20 zone: Device inside the housing

This part is intended for the installation in a suitable housing for the required degree of protection (e.g. control cabinet).

The power connections are excluded => „3.1.1 Climatic environmental conditions“.

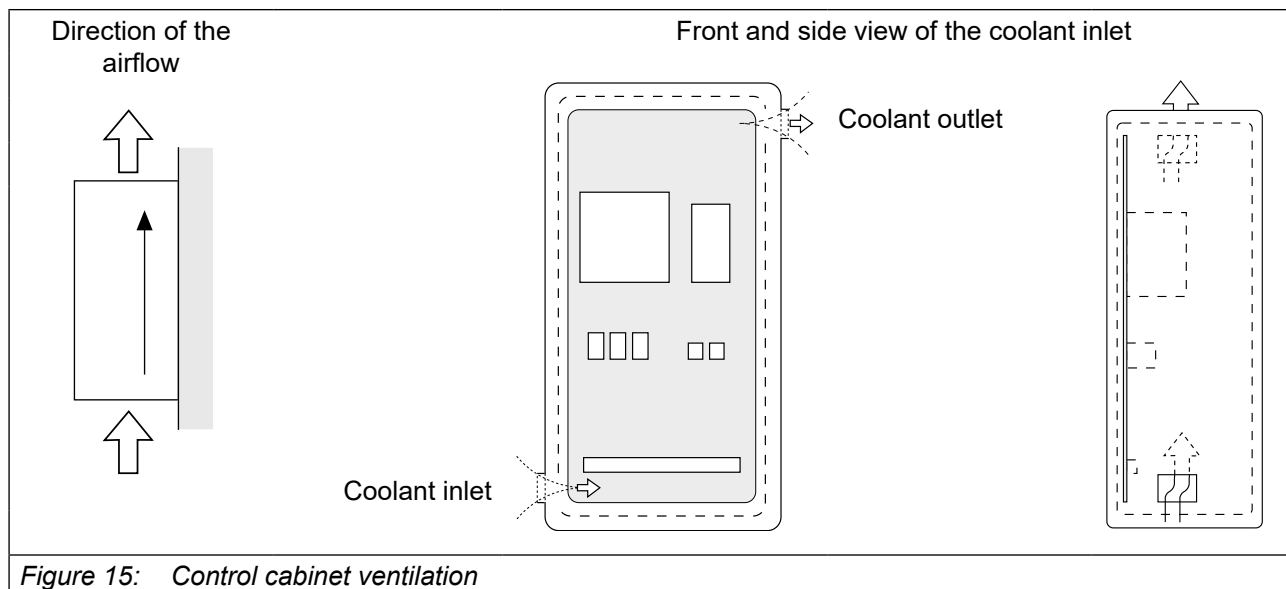
NOTICE

Defect due to continuous splash water !

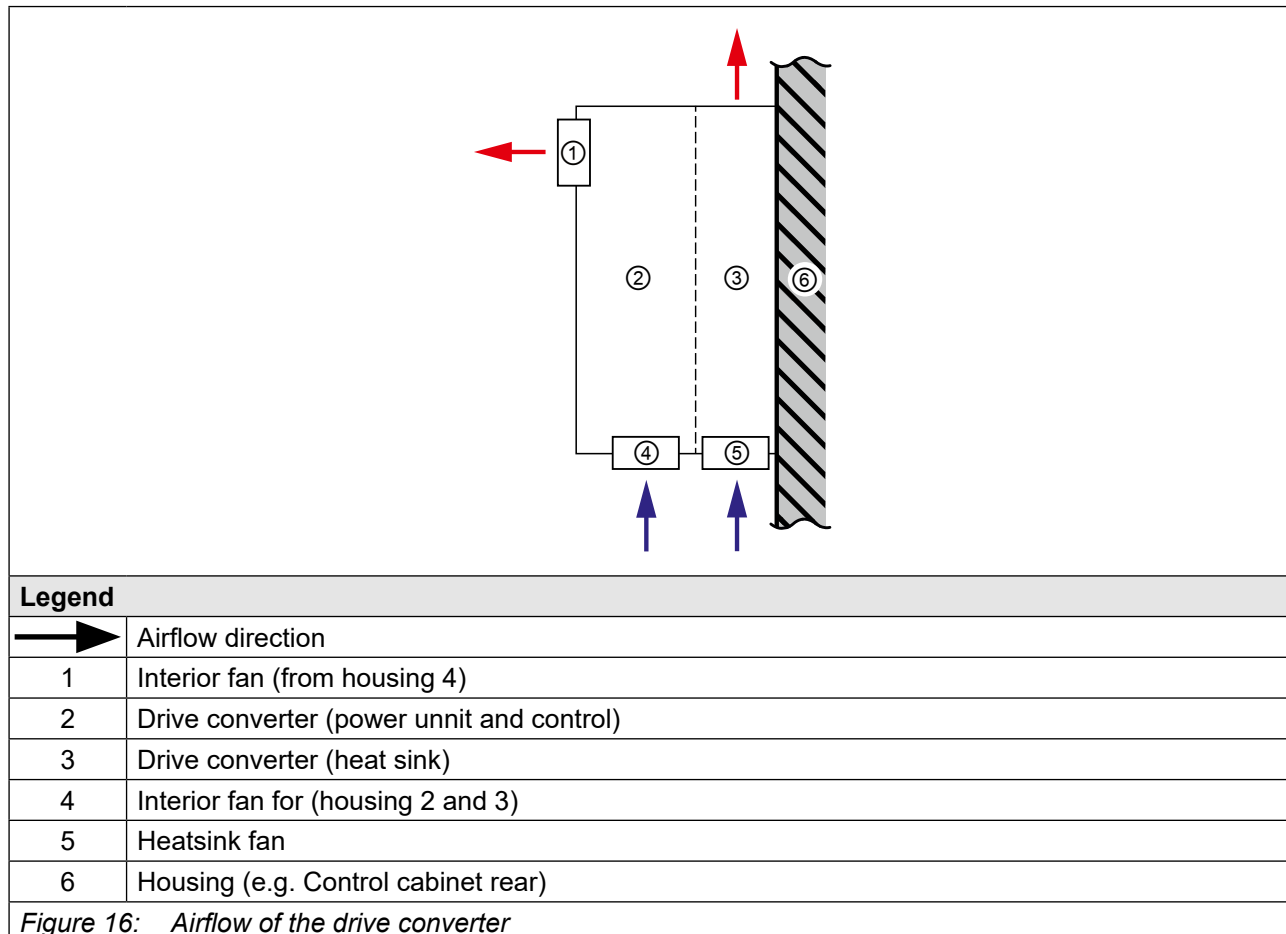
- Never expose the device to continuous splashing water (e.g. direct exposure to rain)!

4.2.6 Control cabinet ventilation

If construction-conditioned the control cabinet cannot be without indoor ventilation, appropriate filters must avoid suction of foreign objects.



4.2.7 Airflow of the drive converter



5 Installation and connection

5.1 Overview of the COMBIVERT F6

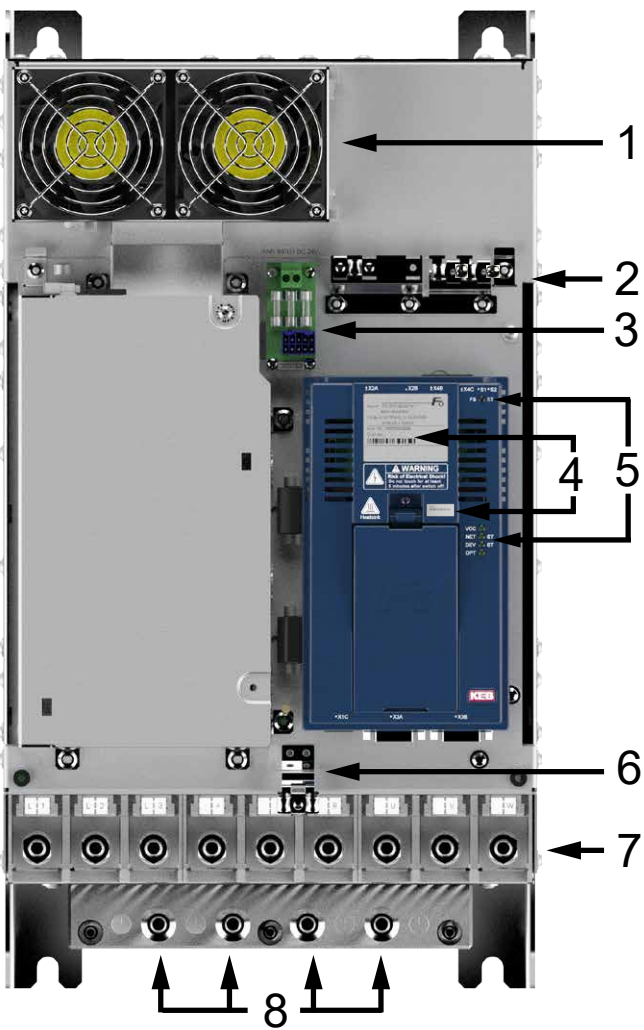
Housing 7		No.	Name	Description
	1	---	Interior fan	
	2/6	---	Shield clamps for shielded control cables	
	3	FAN	External heat sink fan supply ¹⁾	
	4	---	Nameplates	
	5	---	LEDs (see manual for control section chapter => "Overview") <ul style="list-style-type: none">• For control board COMPACT: FS without function.• For control card APPLICATION and PRO: Status indication of the safety module	
	7	X1A	Power circuit terminals for: <ul style="list-style-type: none">• Mains input• Braking resistor• DC voltage interface• Motor connection	
	8	PE	Protective earth; when connecting the protective earth, each terminal may be assigned only once	

Figure 17: F6 housing 7 top view

¹⁾ Observe external heat sink fan supply => „5.3.7 External heat sink fan supply (FAN)“

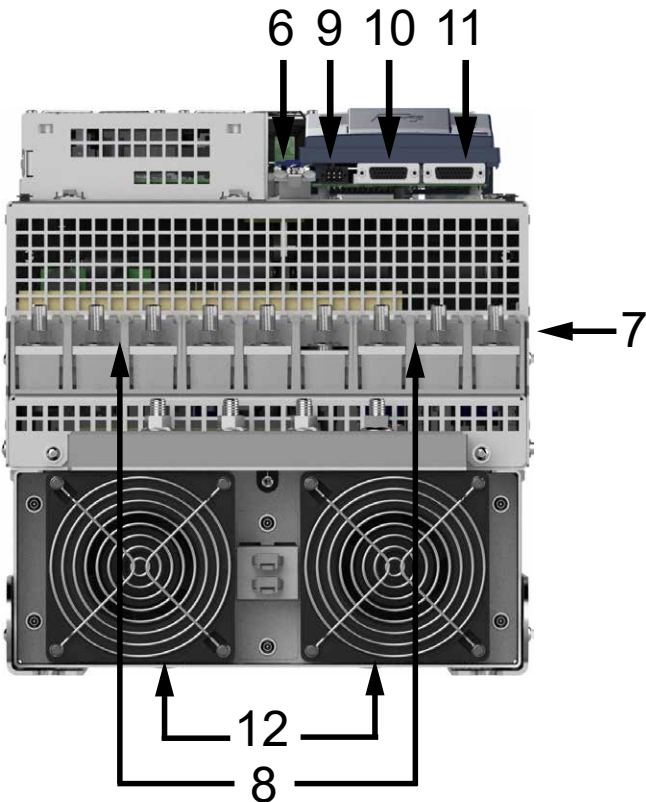
Housing 7	No.	Name	Description
	6	---	Shield clamps for shielded control cables
	7	X1A	Power circuit terminals for: <ul style="list-style-type: none">• Mains input• Braking resistor• DC voltage interface• Motor connection
	8	PE	Protective earth; at connection to protective earth each terminal may be assigned only once
	9	X1C	Terminal for: <ul style="list-style-type: none">• Motor temperature monitoring• Brake control
	10	X3A	Encoder interface channel A
	11	X3B	Encoder interface channel B
	12	---	Heat sink fan

Figure 18: F6 housing 7 front view

Housing 7	No.	Name	Description
	1	---	Interior fan
	2	---	Shield clamps for shielded control cables
	13	S1	Rotary coding switch A
	14	S2	Rotary coding switch B
	15	X4C	Fieldbus interface (out)
	16	X4B	Fieldbus interface (in)
	17	X2B	Safety module
	18	X2A	Control terminal block for <ul style="list-style-type: none">CAN busAnalog inputs and analog outputDigital inputs and outputs24 V DC voltage supply
Figure 19: F6 housing 7 rear view with control board APPLICATION			



Further information can be found in the respective control board manual.



Instructions for use COMBIVERT F6 control board APPLICATION
www.keb.de/fileadmin/media/Manuals/dr/ma_dr_f6-cu-a-inst-20118593_en.pdf



Instructions for use COMBIVERT F6 control board COMPACT
www.keb.de/fileadmin/media/Manuals/dr/ma_dr_f6-cu-k-inst-20144795_en.pdf



Instructions for use COMBIVERT F6 control board PRO
www.keb.de/fileadmin/media/Manuals/dr/ma_dr_f6-cu-p-inst-20182705_en.pdf



5.2 Connection of the power unit

NOTICE

Destruction of the drive controller!

- Never exchange mains input and motor output!

5.2.1 Connection of the voltage supply

The COMBIVERT F6 can be supplied via terminals L1, L2 and L3 (AC power supply) or via terminals + and - (DC power supply with inrush current limitation)

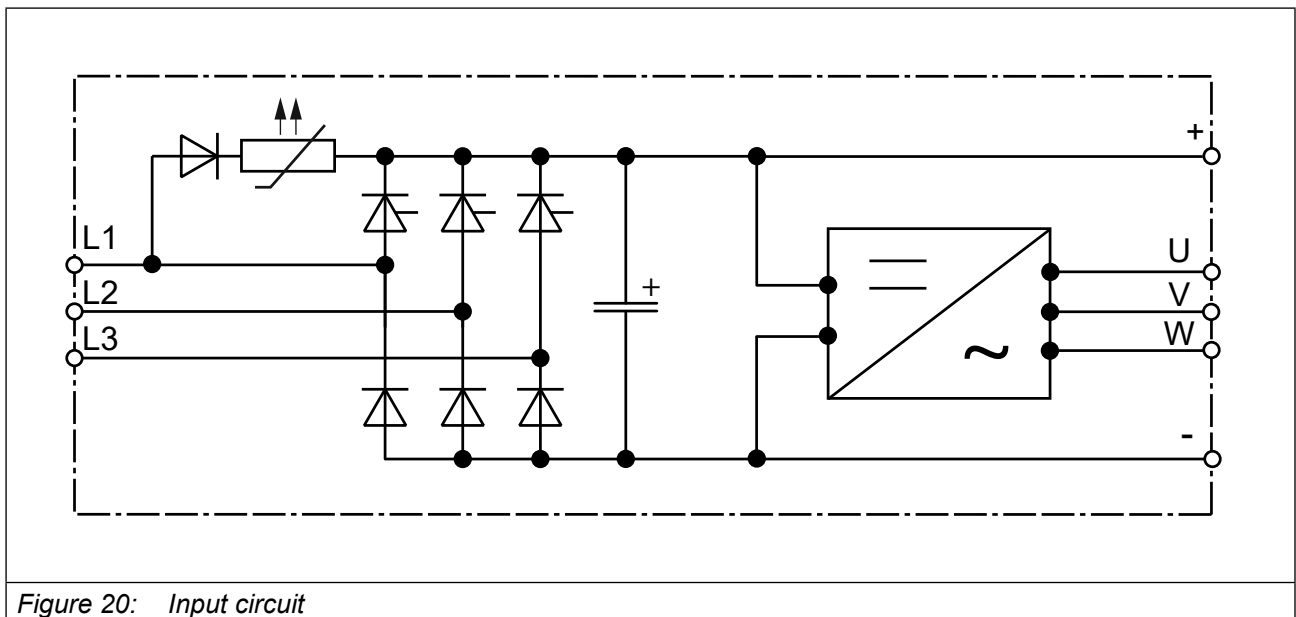


Figure 20: Input circuit

NOTICE

With AC power supply, observe the minimum waiting time between two switch-on procedures!

Cyclical switching off and on of the drive converter leads to temporary high impedance of the PTC precharging resistor. After the PTC precharging resistor has cooled down, it can be restarted without restrictions. The waiting time between two switch-on processes depends on the external capacitance, the AC mains voltage and the ambient temperature.

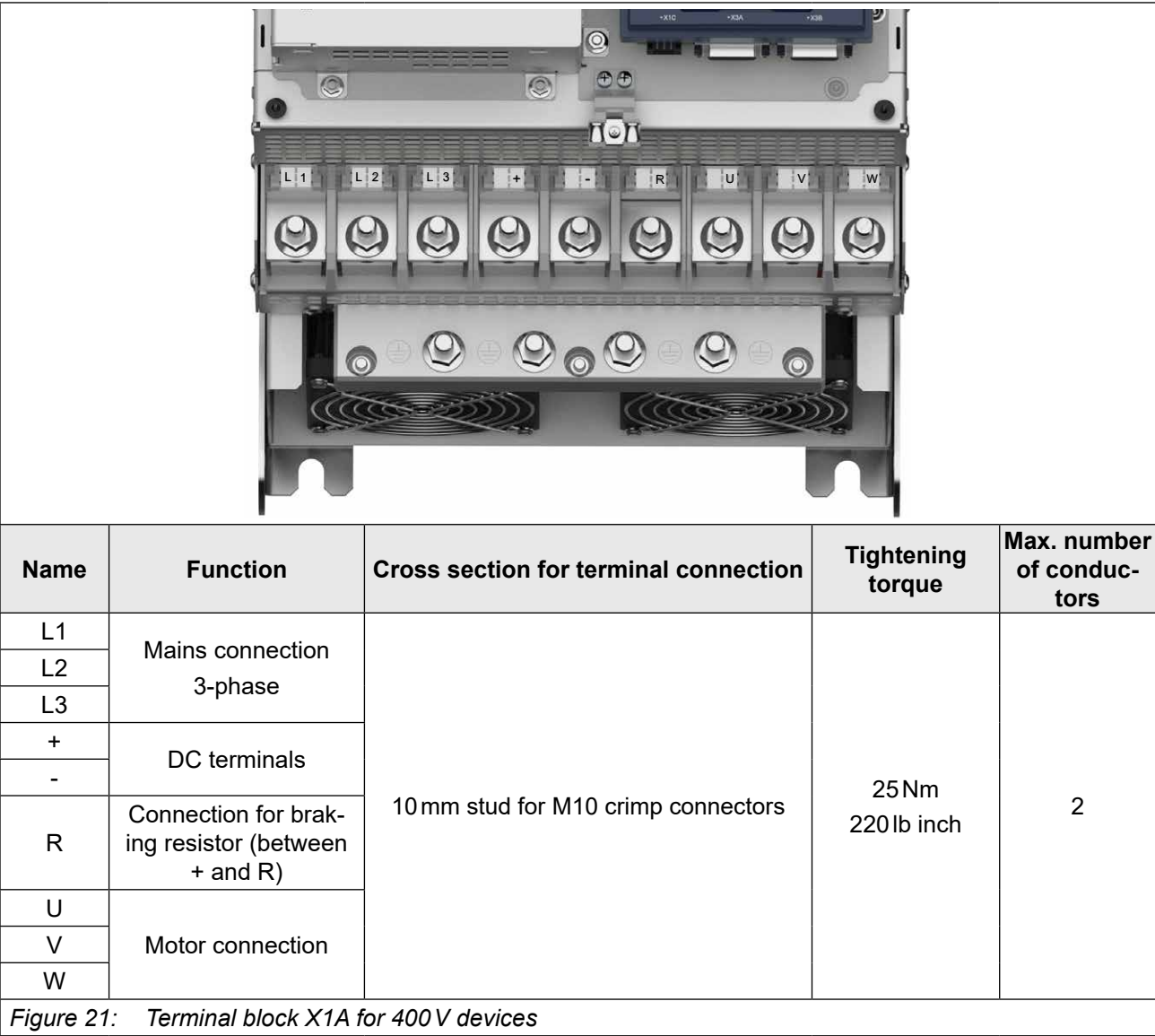
- Without external capacity: 5 min
- With external capacity (additional drive converters): 20 min

NOTICE

No inrush current limitation with DC power supply!

- An external inrush current limiter must be provided for DC power supplies.

5.2.1.1 Terminal block X1A for 400V devices



5.2.2 Protective earth and functional earth



Protective and functional earth must not be connected to the same terminal.

5.2.2.1 Protective earth

The protective earth (PE) serves for electrical safety particularly personal protection in error case.

⚠ CAUTION

Electric shock due to incorrect dimensioning!



► The earthing cross-section complies with [VDE 0100](#) !

Name	Function	Terminal connection	Tightening torque	Max. number of conductors
PE,	Connection for protective earth	10 mm threaded pin for M10 crimp connectors	25 Nm 220 lb inch	1

Figure 22: Connection for protective earth



Incorrect installation of the PE connection

Only M10 threaded pins with nuts may be used as connection for the protective earth!

5.2.1.2 Functional earthing

A functional earthing may also be necessary, if for EMC requirements additional potential equalization between devices or parts of the system must be available.



The use of the functional earth (FE) is not required if the frequency inverter is EMC-technically wired.

The functional earth may not be wired green/yellow!



Notes on EMC-compatible installation can be found here.
www.keb.de/fileadmin/media/Manuals/emv/0000neb0000.pdf



5.3 Mains connection

5.3.1 Supply cable

The conductor cross-section of the supply cable is determined by the following factors:

- Input current of the drive controller
- Used line type
- Installation and ambient temperatures
- The locally valid electrical regulations



The application engineer is responsible for the design!

5.3.2 AC mains connection

5.3.2.1 AC supply 3-phase

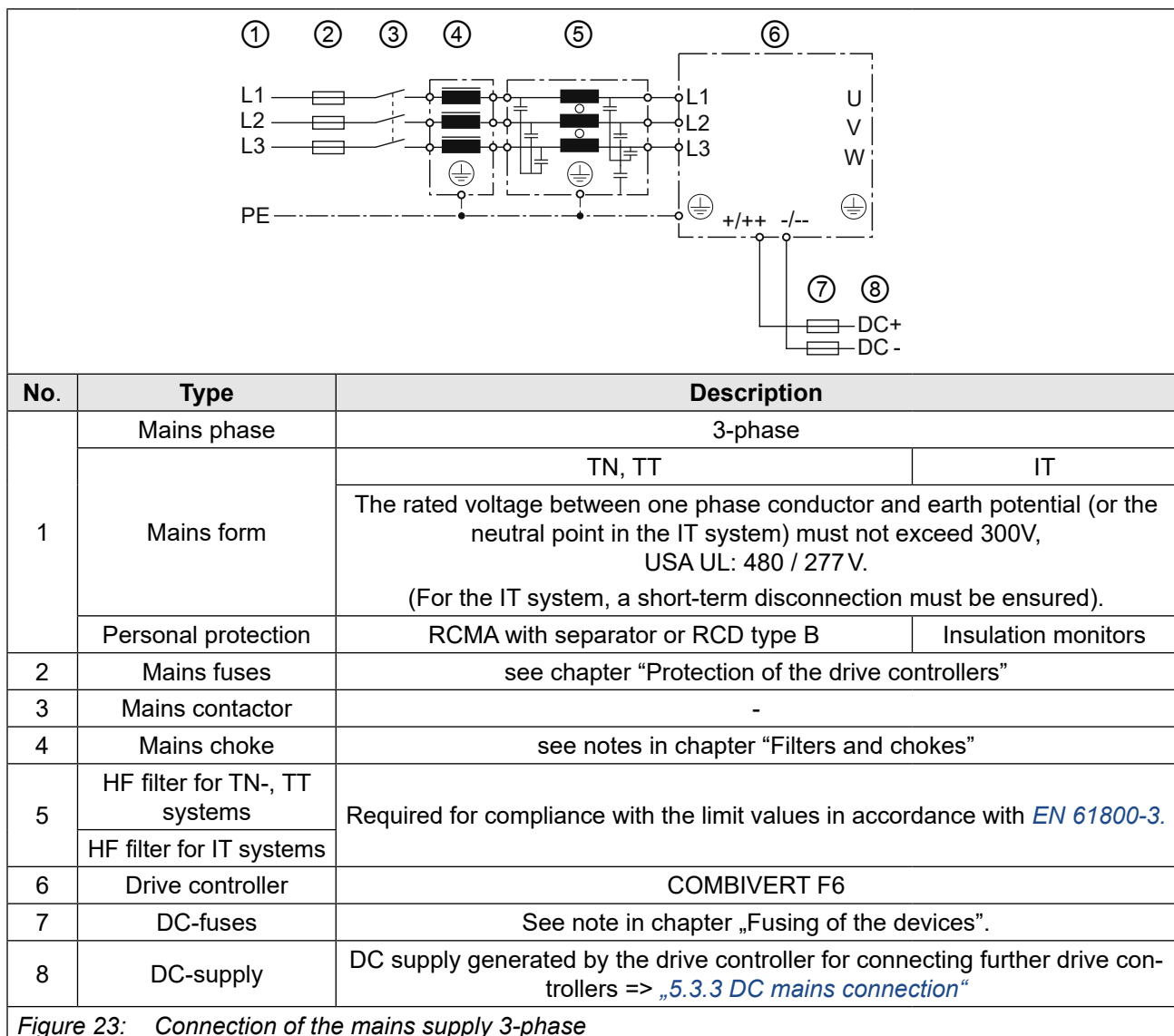
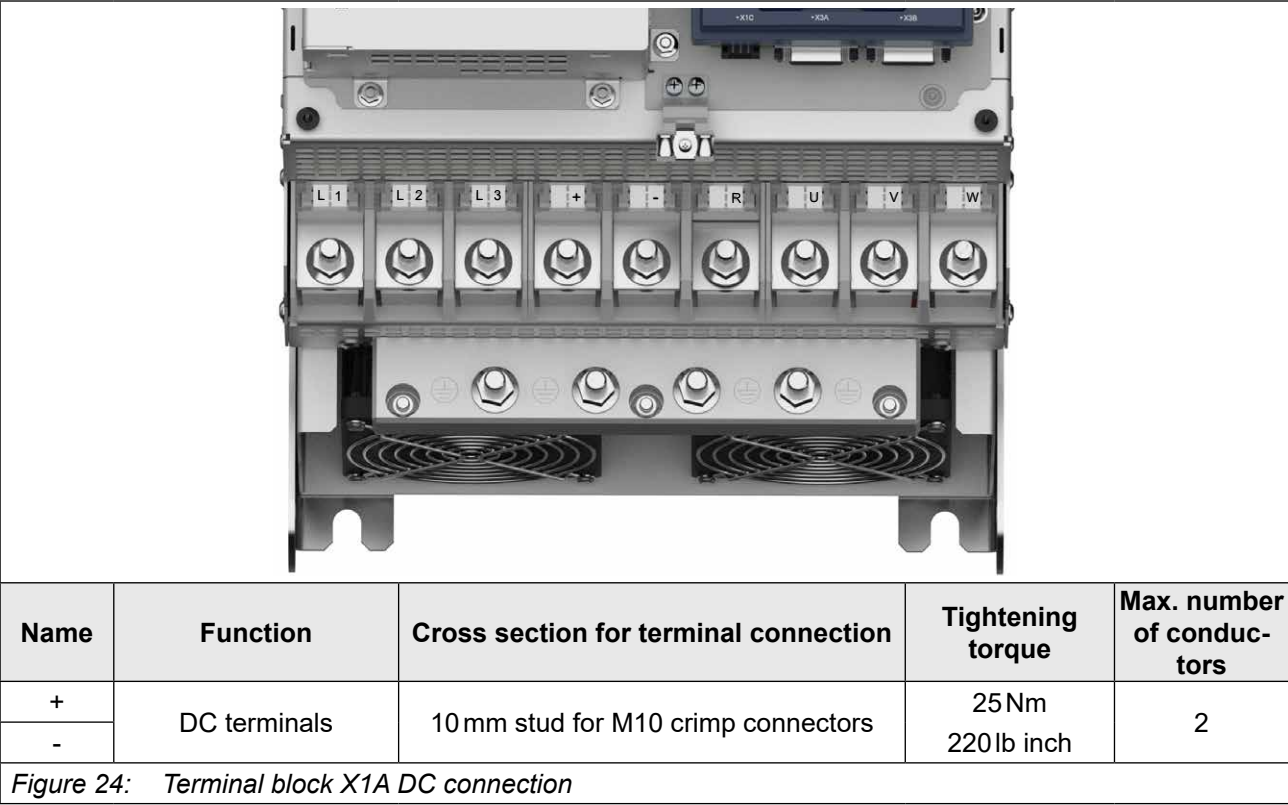


Figure 23: Connection of the mains supply 3-phase

5.3.3 DC mains connection

5.3.3.1 Terminal block X1A DC connection

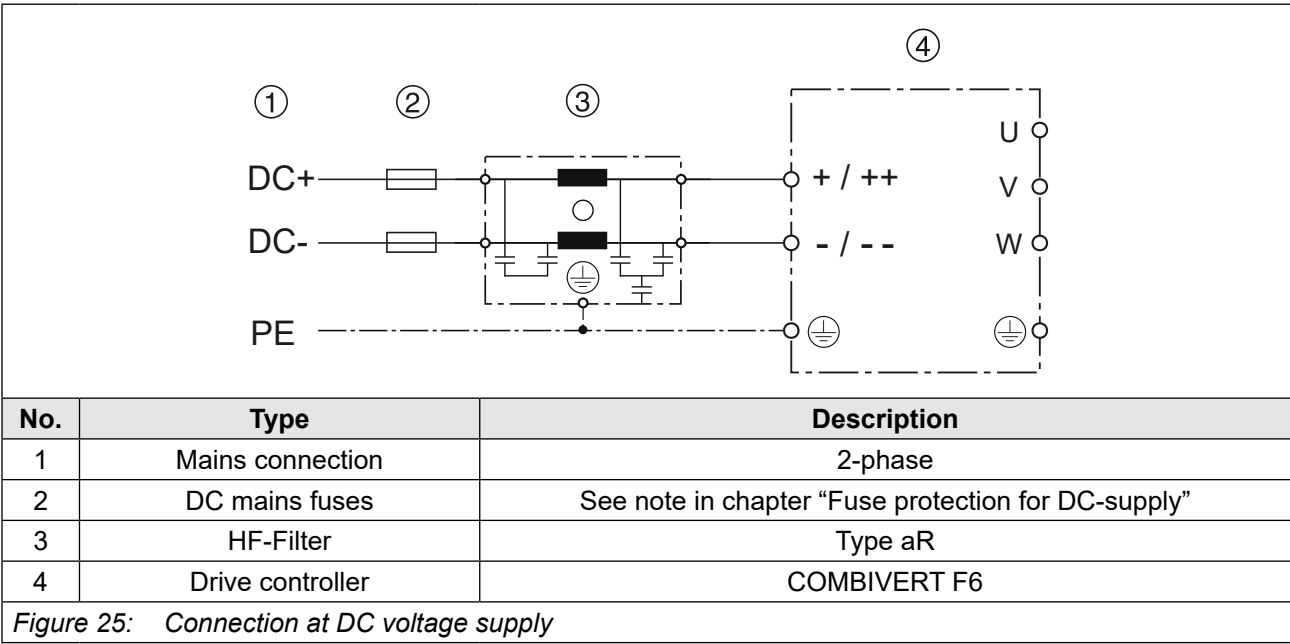


5.3.3.2 Connection at DC voltage supply

NOTICE

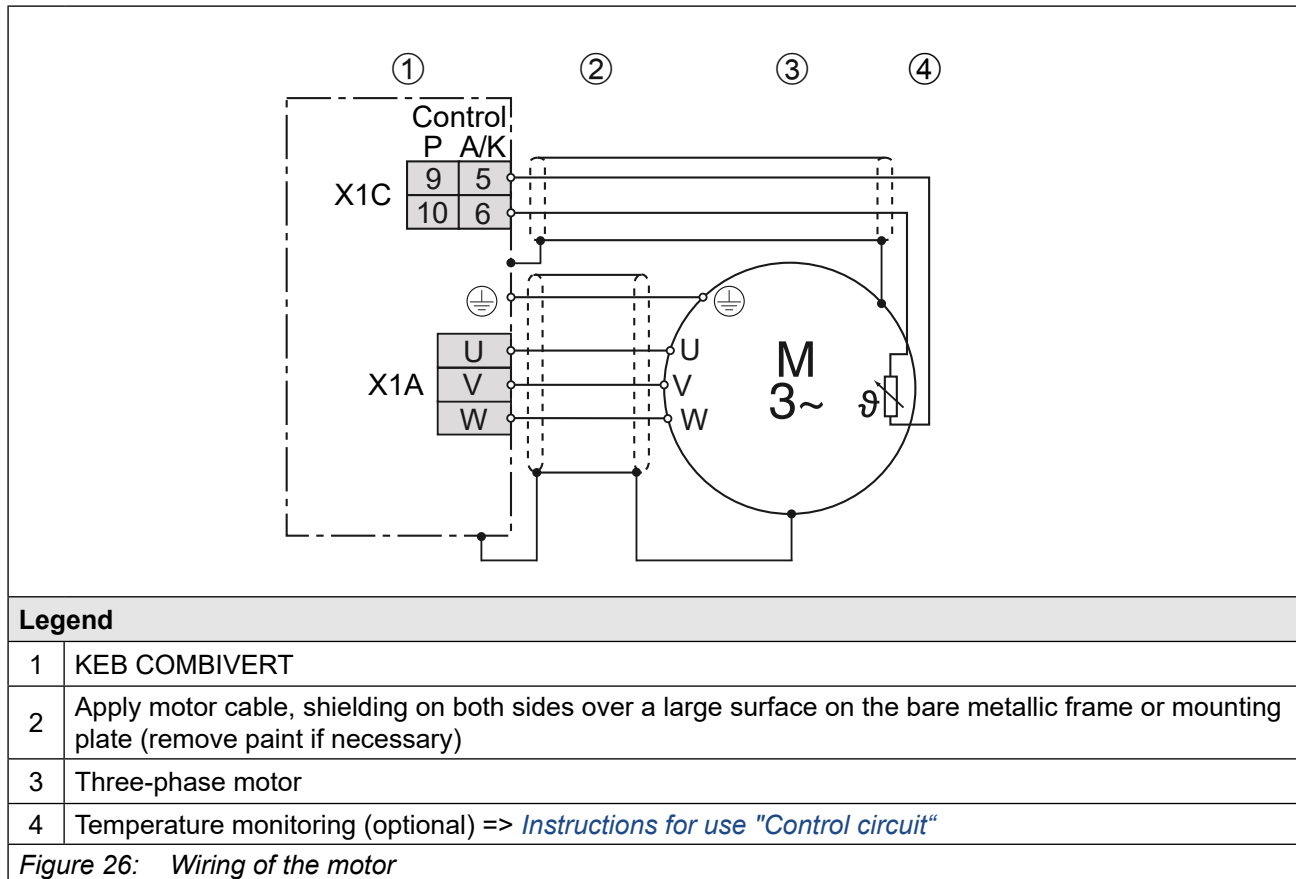
Destruction of the drive controller!

► Never exchange “+ / ++” and “- / --”!

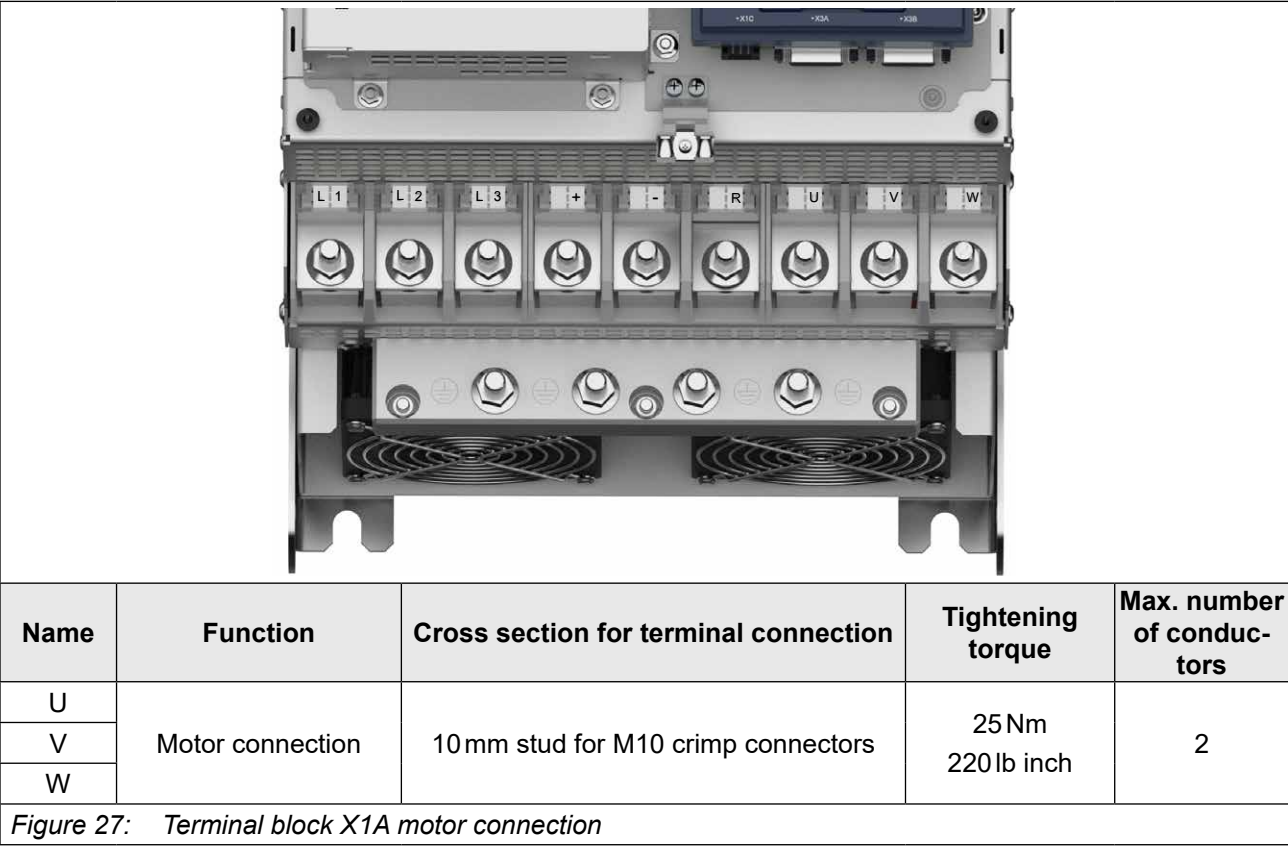


5.3.4 Connection of the motor

5.3.4.1 Wiring of the motor



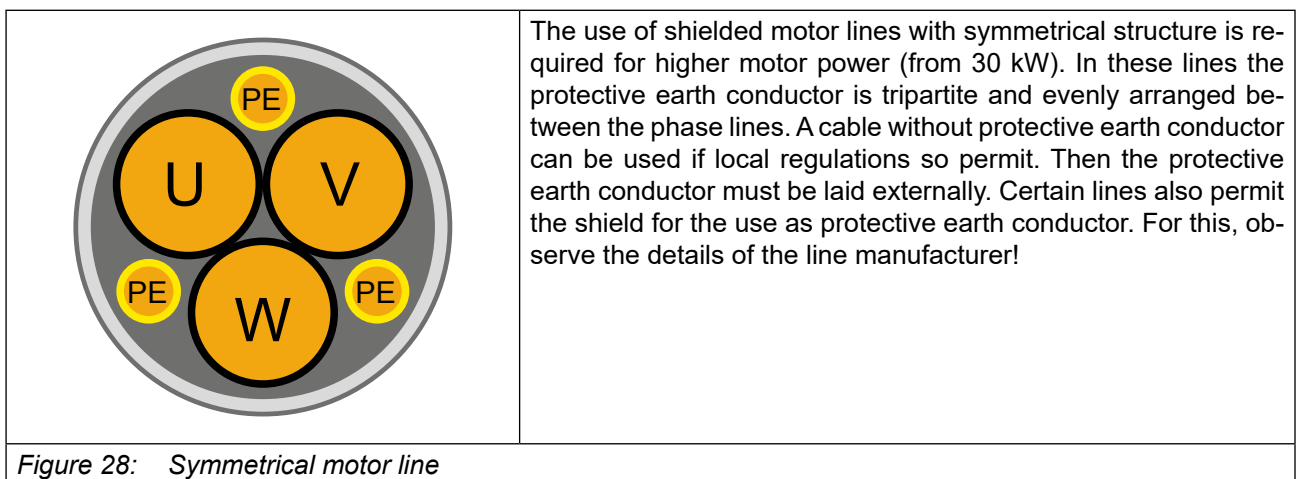
5.3.4.2 Terminal block X1A motor connection



5.3.4.3 Selection of the motor line

The correct cabling as well as the motor line itself play an important part in case of low power in connection with long motor line lengths. Low-capacitance line (phase/phase < 65 pF/m, phase/screen < 120 pF/m) at the inverter output have the following effects:

- allow major motor line lengths („5.3.4.4 Motor cable length and conducted interferences at AC supply“)
- better EMC properties (reduction of the common-mode output currents to earth)



5.3.4.4 Motor cable length and conducted interferences at AC supply

The maximum motor cable length is depending on the capacity of the motor cable as well as on the EMC emitted interference. External measures must be taken here (e.g. the use of a mains filter).



The cable length can be increased significant by using motor chokes or motor filters. KEB recommends the use of motor chokes or filters for a cable length upto 25m.



Further information on the motor cable length can be found in the corresponding filter instructions.

5.3.4.5 Motor cable length for parallel operation of motors

The resulting motor cable length for parallel operation of motors, or parallel installation with multiple cables arises from the following formula:

$$\text{Resulting motor cable length} = \sum \text{single cable length} \times \sqrt{\text{Number of motor cables}}$$

5.3.4.6 Motor cable cross-section

The motor cable cross-section is dependent

- on the characteristic of the output current (e.g. harmonic content)
- on the real effective value of the motor current
- on the cable length
- on the type of the used cable
- on the ambient conditions such as bundling and temperature

NOTICE

Incorrect behavior of the motor!

- The connecting-up instructions of the motor manufacturer are always generally valid!

NOTICE

Protect motor against voltage peaks!

- **Drive controllers** switch at the output with high dv/dt . Voltage peaks that endanger the insulation system at the motor can occur especially in case of long motor cables (>15 m). A motor choke, a dv/dt -filter or sine-wave filter can be used to protect the motor with regard to the operating mode.

5.3.4.7 Connection of the temperature monitoring and brake control (X1C)

A switchable temperature evaluation is implemented in the COMBIVERT.

There are different types for the evaluation available. These are depending on the control board => [instruction manual „control board“](#).

The desired operating mode can be adjusted via software (dr33). If the evaluation is not required, it must be deactivated via software (parameter pn12 = 7) => [Programming manual](#)

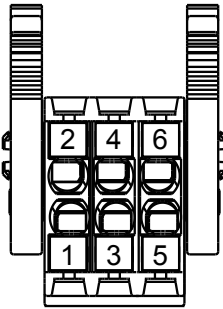
X1C	PIN	Name	Description
	1	BR+	Brake control / output +
	2	BR-	Brake control / output -
	3	reserved	—
	4	reserved	—
	5	TA1	Temperature detection / output +
	6	TA2	Temperature detection / output -

Figure 29: Terminal block X1C for control board APPLICATION and COMPACT

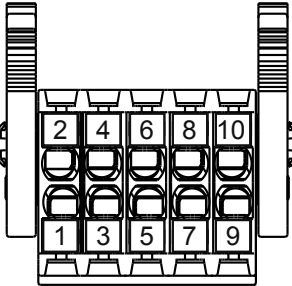
X1C	PIN	Name	Description
	1	BR+	Brake control / output +
	2	BR-	Brake control / output -
	3	0V	For supply of the checkback inputs
	4	24Vout	
	5	DIBR1	Checkback input 1 for brake and relay
	6	DIBR2	Checkback input 2 for brake and relay
	7	reserved	—
	8	reserved	—
	9	TA1	Temperature detection / output +
	10	TA2	Temperature detection / output -

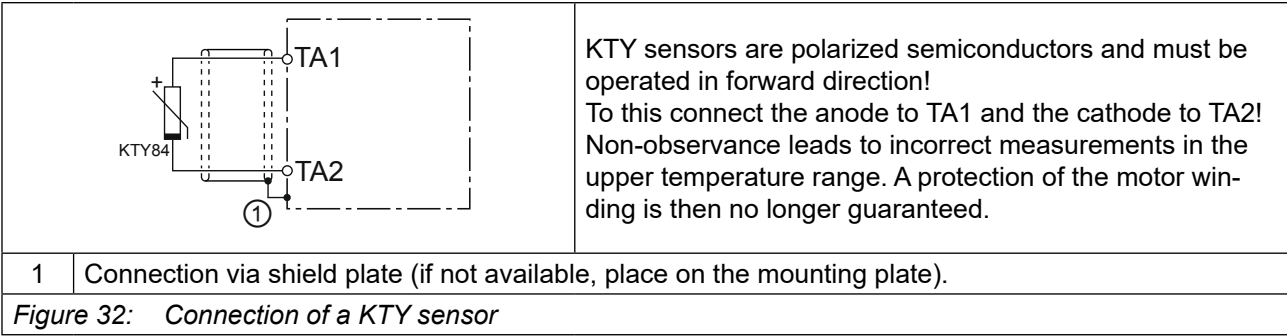
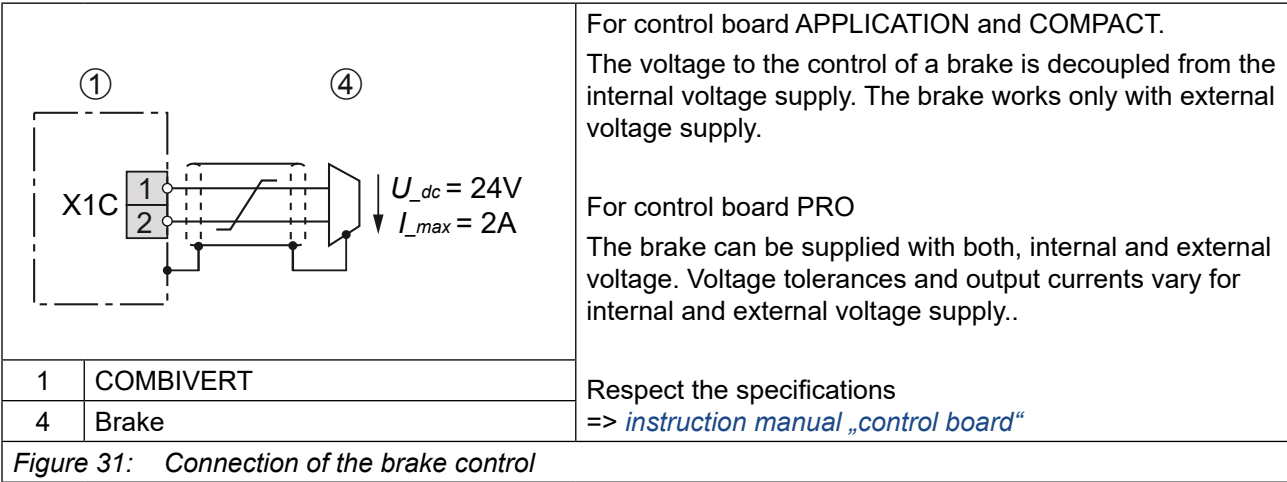
Figure 30: Terminal block X1C for control board PRO

NOTICE

Malfunctions due to incorrect line or laying!

Malfunctions of the control due to capacitive or inductive coupling.

- Do not route cables from the motor temperature sensor (also shielded) together with control cables.
- Cables from the motor temperature sensor within the motor cables may only be used with double shielding!
- The input of the temperature detection has basic isolation.



NOTICE

No protection of the motor winding in case of wrong connection.

- Operate KTY sensors in forward direction.
- KTY sensors may not be combined with other detections.



Further information about the wiring of the temperature monitoring and the brake control have to be observed in the respective control unit manual.

5.3.5 Connection and use of a braking resistor

⚠ CAUTION**Fire risk by using brake resistors !**

- ▶ The risk of fire can be significantly reduced by using „intrinsically safe braking resistors“ or by using suitable monitoring functions / circuits.

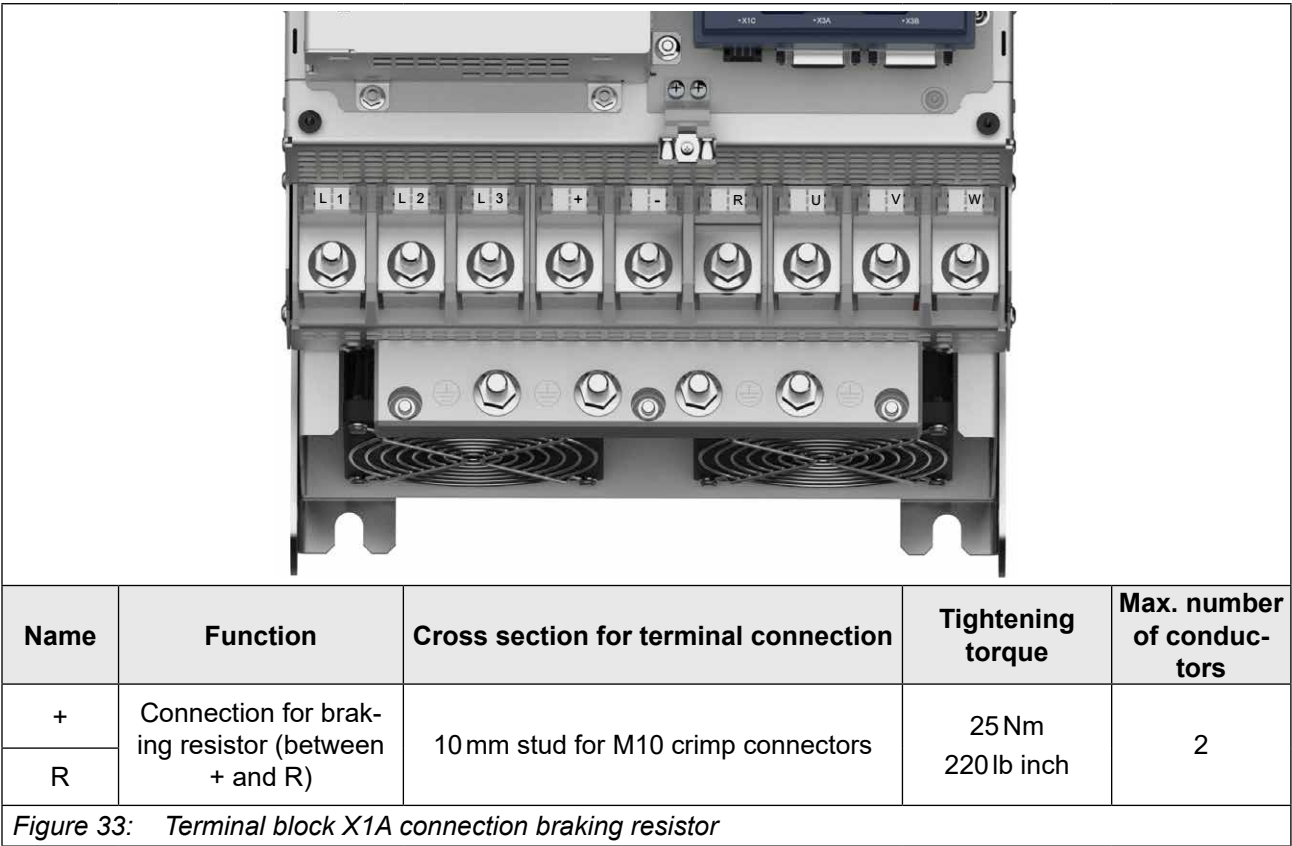
NOTICE**Destruction of the frequency inverter if the value has fallen below the minimum brake resistance value!**

- ▶ The minimum brake resistance value must not fall below!
„3.2 Device data of the High Speed Drive devices“

⚠ CAUTION**Hot surfaces caused by load of the braking resistor!****Burning of the skin!**

- ▶ Cover hot surfaces safe-to-touch.
- ▶ Before touching, check the surface.
- ▶ If necessary, attach warning signs on the system.

5.3.5.1 Terminal block X1A connection braking resistor



At devices with sub-mounted braking resistors, there is no electrical connection to the braking transistor at terminal R!

5.3.5.2 Use of non-intrinsically safe braking resistors

⚠ WARNING**Use of non-intrinsically safe braking resistors****Fire or smoke emission in case of overload or error!**

- ▶ Only use braking resistors with temperature sensor.
- ▶ Evaluate temperature sensor.
- ▶ Trigger an error at the drive controller (e.g. external input).
- ▶ Switch off input voltage (e.g. input contactor).
- ▶ Connection examples for non-intrinsically safe braking resistors
=> *Instructions for use "Installation braking resistors".*



Instructions for use "Installation braking resistors"

https://data.keb.de/fileadmin/media/Manuals/dr/ma_dr_braking-resistors-20116737_en.pdf

5.3.6 DC-bus connection

The DC link of several drive controllers are coupled in a DC-bus connection. This enables energy to be exchanged between the devices and increases the energy efficiency of the application.

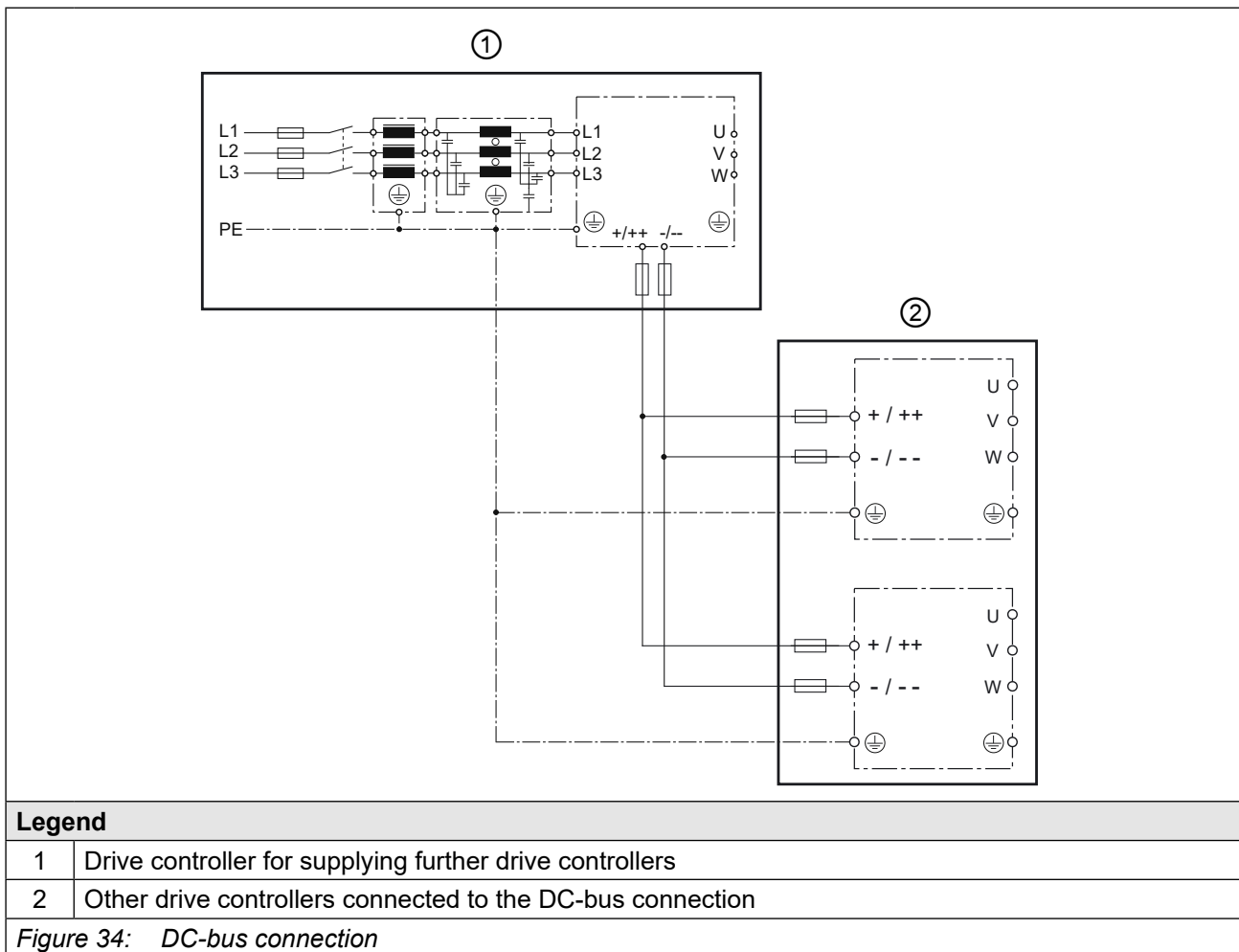
As part of a DC-bus connection, this drive controller can either be supplied via the DC terminals => „[5.3.3 DC mains connection](#)“ or supply other drive controllers via the DC terminals => „[5.3.2 AC mains connection](#)“.



KEB drive converters meet the requirements of the EMC product standard EN IEC 61800-3 for DC power supplies. Due to the large number of possible interconnection options in the DC network, the user is responsible for ensuring the conformity of the overall system.

The following additional safety instructions must be observed when using this drive controller in a DC-bus connection:

- This drive controller may only be operated together with other F6 and S6 drive controllers of the 400V class in a DC-bus connection.
- This drive controller must be installed in an enclosure.
- This drive controller must be protected with fuses at the DC terminals => „[3.2.6.2 Protecting HSD devices with DC power supply](#)“.
- If one fuse in the DC-bus connection blows as a result of a short circuit, all fuses in the DC-bus connection should be replaced due to the risk of prior damage.
- The parameterisation of the input phase failure detection must be adapted => F6 Programming manual.



① When using this drive controller to supply other drive controllers via the DC terminals, the following must also be observed:

- The maximum prechargeable total capacity (internal capacity + external capacity) must not be exceeded => „3.3.2.1 DC link / braking transistor function“.
- The minimum waiting time between two precharging procedures must be observed => „5.2.1 Connection of the voltage supply“.
- Drive controllers supplied via the DC terminals must not be loaded during precharging.
- Overloading of the rectifier must be prevented by the user => „3.2.4 Overview of rectifier data for HSD devices“.

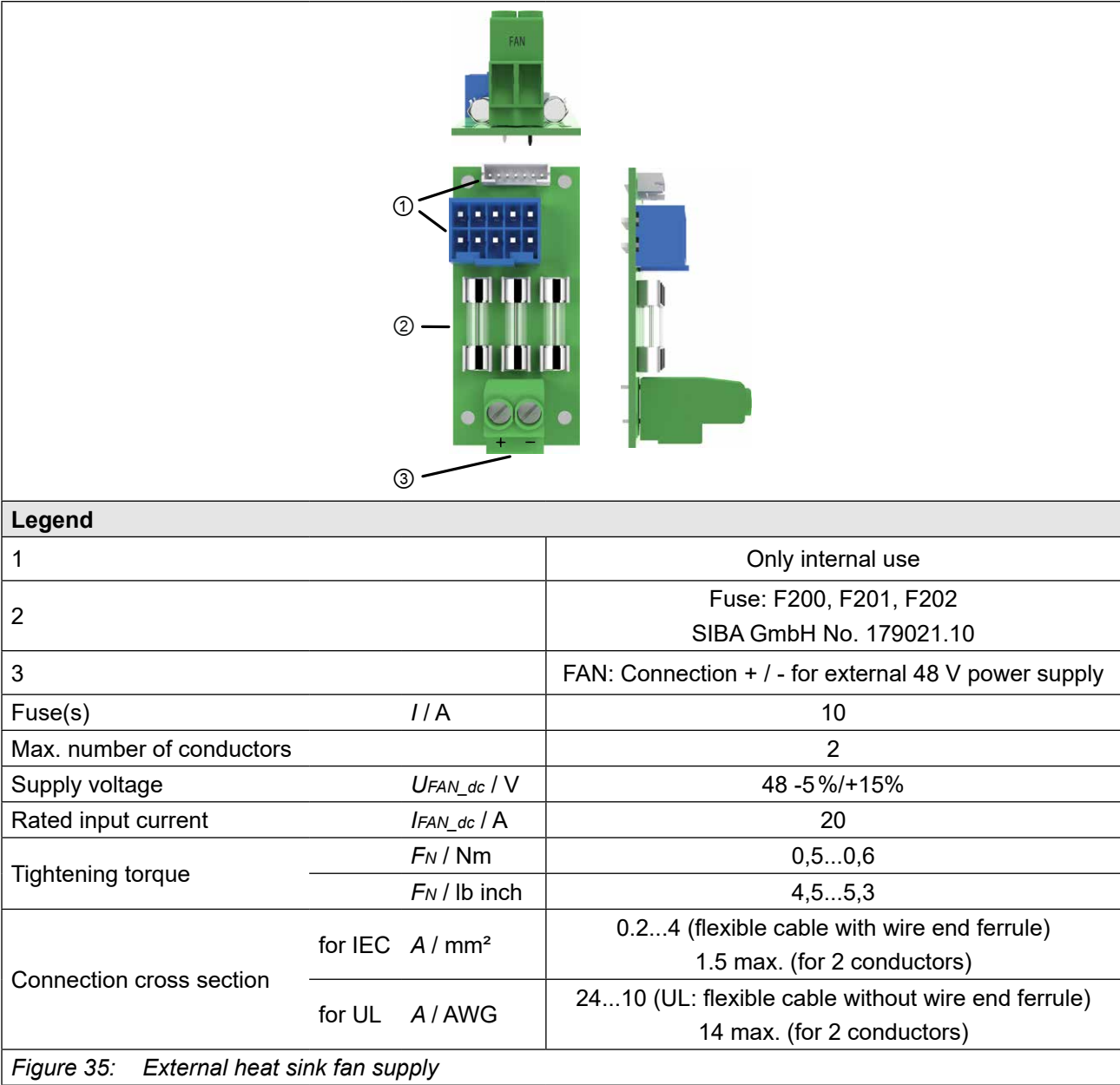
② When supplying this drive controller via the DC terminals, the following must also be observed:

- The drive controller must be pre-charged by the supplying drive controller or an external pre-charging module.

5.3.7 External heat sink fan supply (FAN)



The external heat sink fan supply is only available for air-cooled devices.





The control board and heat sink fans should be powered by separate external voltage sources.

In the event of a fault in the heat sink fans, this provides an uninterrupted supply of power to the control system.

NOTICE

Use of unsuitable voltage sources!

Electric shock!

- ▶ Only voltage sources (PELV) according to VDE 0100 permitted.
- ▶ Ensure that the overvoltage category of the voltage supply is sufficient.
- ▶ Observe the triggering characteristics of the fuses when selecting the voltage source of the heat sink fan supply.

5.4 Accessories

5.4.1 Filters and chokes

Voltage class	Drive controller size	HF filter	Mains choke 50 Hz / 4 % U_k
400V	26	<ul style="list-style-type: none"> • 26E4T60-1001 • 26E4T60-1051 • 27E6T60-1150 • 27E6T60-3000 	26Z1B04-1000
	27	<ul style="list-style-type: none"> • 27E6T60-1150 • 27E6T60-3000 • 28E4T60-1001 • 28E4T60-1051 	27Z1B04-1000
	28	<ul style="list-style-type: none"> • 28E4T60-1001 	28Z1B06-1000

Table 32: Filters and chokes

NOTICE

Overheating of the back mount filter!

- The use of back mount filters for drive controllers with the material number xxF6xxx-xxx9 (fluid cooler water, built-in version, sub-mounted braking resistors) leads to overheating and is not permissible!



The specified filters and chokes are designed for rated operation.

5.4.2 Seal for IP54-ready devices

Name	Material number
Flat seal IP54 air cooler	70F6T45-0010

Table 33: Seal for IP54-ready devices

5.4.3 Side-mounted braking resistors



Technical data and design for non-intrinsically safe braking resistors

https://data.keb.de/fileadmin/media/Manuals/dr/ma_dr_braking-resistors-20116737_en.pdf



6 Operation of Liquid-Cooled Devices

6.1 Water-cooled devices

The use of water-cooled KEB COMBIVERT drive converters is offered, because there are process-caused coolants available with some applications. However, the following instructions must be observed.

6.1.1 Heat sink and operating pressure

Design system	Material	max. operating pressure	Connection
Aluminium heat sink	Aluminium -1,67 V	10 bar	=> „6.1.4 Connection of the cooling system“

NOTICE

Deformation of the heat sink!

- In order to avoid a deformation of the heat sink and the damages thereby, the indicated maximum operating pressure may not be exceeded briefly also by pressure peaks.
- Observe the Pressure Equipment Directive 2014/68/EU!

6.1.2 Materials in the cooling circuit

For the screw connections and also for the metallic articles in the cooling circuit which are in contact with the coolant (electrolyte) a material is to be selected, which forms a small voltage difference to the heat sink in order to avoid contact corrosion and/or pitting corrosion (electro-chemical voltage series, see the following table). The specific case of application must be checked by the customer in tuning of the complete cooling circuit and must be classified according to the used materials. With hoses and seals take care that halogen-free materials are used.

A liability for occurring damages by wrongly used materials and from this resulting corrosion cannot be taken over!

Material	formed ion	Standard potential	Material	formed ion	Standard potential
Lithium	Li+	-3.04 V	Nickel	Ni ²⁺	-0.25 V
Potassium	K+	-2.93 V	Tin	Sn ²⁺	-0.14 V
Calcium	Ca ²⁺	-2.87 V	Lead	Pb ³⁺	-0.13 V
Sodium	Na+	-2.71 V	Iron	Fe ³⁺	-0.037 V
Magnesium	Mg ²⁺	-2.38 V	Hydrogen	2H+	0.00 V
Titan	Ti²⁺	-1.75 V	Stainless steel (1.4404)	various	0.2...0.4 V
Aluminium	Al ³⁺	-1.67 V	Copper	Cu ²⁺	0.34 V
Manganese	Mn ²⁺	-1.05 V	Carbon	C ²⁺	0.74 V
Zinc	Zn ²⁺	-0.76 V	Silver	Ag+	0.80 V

continued on the next page

Material	formed ion	Standard potential	Material	formed ion	Standard potential
Chrome	Cr ³⁺	-0.71 V	Platinum	Pt ²⁺	1.20 V
Iron	Fe ²⁺	-0.44 V	Gold	Au ³⁺	1.42 V
Cadmium	Cd ²⁺	-0.40 V	Gold	Au ⁺	1.69 V
Cobalt	Co ²⁺	-0.28 V			

Table 34: Electrochemical series / standard potentials against hydrogen

6.1.3 Requirements for the coolant

The requirements for the coolant depend on the ambient conditions as well as the used cooling system.

General requirements for the coolant:

Requirement	Description
Standards	Corrosion protection according to EN 12502-1...5 , water treatment and use of materials in cooling systems according to VGB S 455 P .
VGB Cooling water directive	The VGB cooling water directive (VGB S 455 P) contains instructions about common process technology of the cooling. Particularly the interactions between cooling water and components of the cooling system are described.
Abrasive substances	Abrasive substances as used in abrasive (quartz sand), clogging the cooling circuit.
Hard water	Cooling water may not cause scale deposits or loose excretions. The total hardness should be between 7...20 °dH, the carbon hardness at 3...10 °dH.
Soft water	Soft water (<7°dH) corrodes the material.
Frost protection	An appropriate antifreeze must be used for applications when the heat sink or the coolant is exposed temperatures below zero. Use only products of one manufacturer for a better compatibility with other additives. KEB recommends the antifreeze Antifrogen N from Clariant with a maximum volume content of 52 %.
Corrosion protection	Additives can be used as corrosion protection. In connection with frost protection the antifreeze must have a concentration of 20...25 Vol %, in order to avoid a change of the additives. Alternatively, an antifreeze / glycol with a concentration of 20% ... max. vol 52% can be used. If antifreeze is used, the water does not need to be provided with additional additives.

Table 35: Requirements for the coolant

Special requirements for open and half-open cooling systems:

Requirement	Description
Impurities	Mechanical impurities in half-open cooling systems can be counteracted when appropriate water filters are used.
Salt concentration	The salt content can increase through evaporation at half-open systems. Thus the water is more corrosive. Adding of fresh water and removing of process water works against.
Algae and myxobacteria	Algae and myxobacteria can arise caused by increased water temperature and contact with atmospheric oxygen. The algae and myxobacteria clog the filters and obstruct the water-flow. Biocide containing additives can avoid this. Especially at longer OFF periods of the cooling circuit preventive maintenance is necessary.
Organic materials	The contamination with organic materials must be kept as small as possible, because separate slime can be caused by this.

Table 36: Special requirements for open and half-open cooling systems



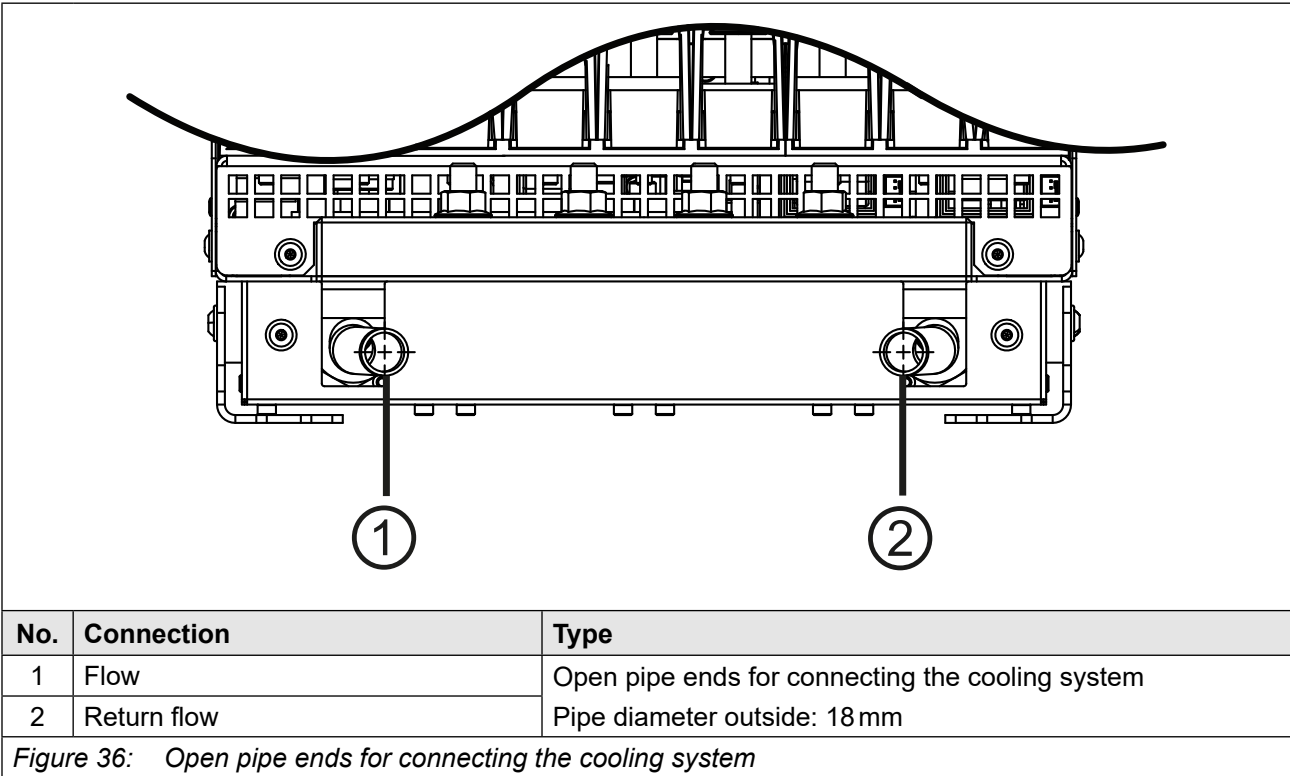
Damages at the device which are caused by clogged, corroded heat sinks or other obvious operating errors, leads to the loss of the warranty claims.

6.1.4 Connection of the cooling system

The connection to the cooling system can occur as closed or open cooling circuit. The connection to a closed cycle cooling circuit is recommended, because the danger of contamination of coolant is very small. Preferably also a monitoring of the pH value of the coolant should be installed.

Pay attention to a corresponding conductor cross-section at required equipotential bonding in order to avoid electro-chemical procedures.

Other elements in the cooling circuit such as pumps, shut-off valves, ventilation etc. must be attached according to the cooling system and the local conditions.



To connect the cooling system, KEB recommends the use of functional nuts, e.g. from the manufacturer "Parker", type FMxxL71 (xx = pipe diameter).
The recommended tightening torque is 80Nm.



KEB recommends the use of a volume flow monitor to monitor the volume flow in the cooling system.

6.1.5 Coolant temperature and moisture condensation

The flow temperature should be selected depending on the volume flow so that the heat sink temperature is always 10 K below the overtemperature level (OH) during rated operation. This avoids sporadic shutdown.

The maximum heat sink temperature can be found in chapter => „3.3.1 Switching frequency and temperature“.

6.1.5.1 Condensation

A temperature difference between drive converter and ambient temperature can lead to condensation at high humidity.

Moisture condensation is dangerous for the drive converter. The drive converter can be destroyed through occurring short-circuits.

NOTICE

Destruction of the drive converter due to short circuit!

► Avoid any condensation.

6.1.5.2 Supply of temper coolant

- The supply of optimally tempered coolant is possible by using heaters in the cooling circuit to control the coolant temperature.
- The following dew point table shows the coolant inlet temperature depending on the ambient temperature and air humidity.

Air humidity / %	10	20	30	40	50	60	70	80	90
Ambient temperature / °C									
-10	-34	-26	-22	-19	-17	-15	-13	-11	-11
-5	-29	-22	-18	-15	-13	-11	-8	-7	-6
0	-26	-19	-14	-11	-8	-6	-4	-3	-2
5	-23	-15	-11	-7	-5	-2	0	2	3
10	-19	-11	-7	-3	0	1	4	6	8
15	-18	-7	-3	1	4	7	9	11	13
20	-12	-4	1	5	9	12	14	16	18
25	-8	0	5	10	13	16	19	21	23
30	-6	3	10	14	18	21	24	26	28
35	-2	8	14	18	22	25	28	31	33
40	1	11	18	22	27	31	33	36	38
45	4	15	22	27	32	36	38	41	43
Coolant inlet temperature / °C									

Table 37: Dew point table



Information on coolant management is given in the following document

www.keb.de/fileadmin/media/Techinfo/dr/an/ti_dr_an-liquid-cooling-00004_en.pdf



NOTICE

Destruction of the heat sink at storage / transport of water-cooled devices!

Observe the following points when storing water-cooled devices:

- ▶ Completely empty the cooling circuit
- ▶ Blow out the cooling circuit with compressed air

NOTICE

Destruction of the drive converter due to condensation!

- ▶ Use only NC valves!

6.1.6 Permissible volume flow for water cooling

The volume flow rate in the following table must be observed.

Permissible volume flow		26	28
Min. volume flow	$Q_{min} / l/min$	20	25
Max. volume flow	$Q_{max} / l/min$	30	30
Table 38: Permissible volume flow for water cooling			



The volume flow depends on the total power dissipation.

=> „6.1.7 Coolant heating“

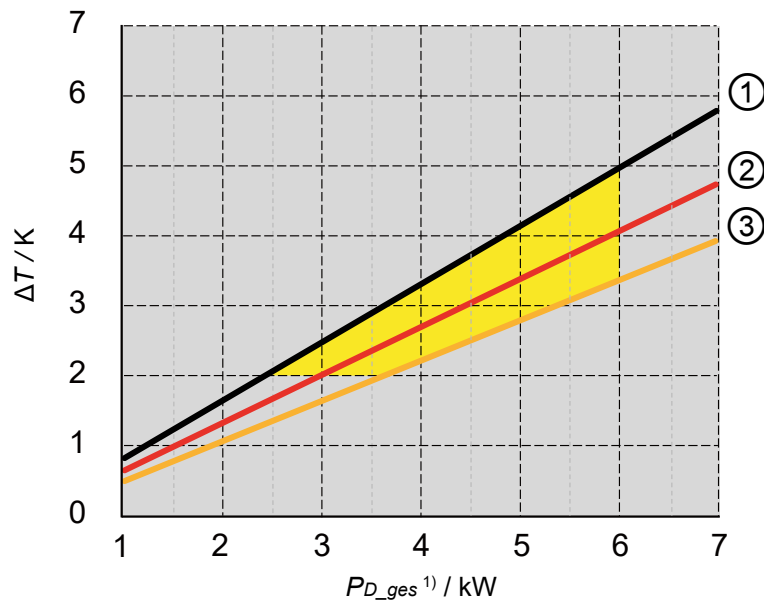
NOTICE

Destruction of the heat sink due to erosion!

- ▶ The maximum permissible volume flow must not be exceeded.

6.1.7 Coolant heating

Volume flow depending on the total power dissipation and temperature difference between flow and return flow.



Legend

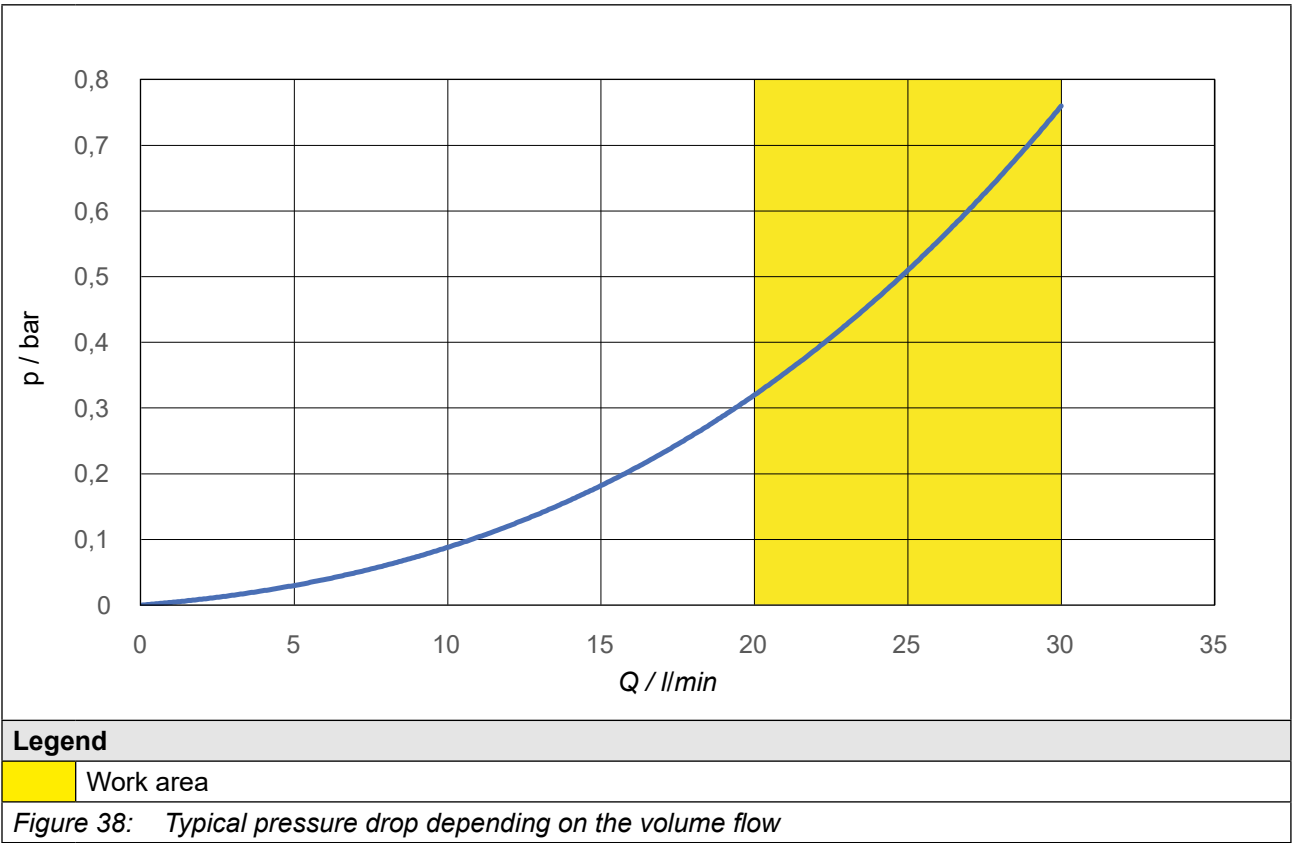
	Work area
1	20 l/min
2	25 l/min
3	30 l/min

Figure 37: Volume flow depending on the total power dissipation P_{D_tot} and temperature difference with water-glycol mixture

¹⁾ P_{D_tot} can be higher than the power dissipation P_D during rated operation due to overload, higher switching frequency or sub-mounted braking resistors.

6.1.8 Typical pressure drop of the heat sink

- The curve characteristic shown below is valid for 25 °C flow temperature and a glycol content of 52 %.
- If higher flow temperatures are used, the pressure drop in the system decreases.
- This also applies to cooling media such as water or another glycol mixture.
- A glycol mixture from Clariant in a ratio of 52 % or 33 % is recommended.



7 Approvals and certifications

7.1 CE marking


The drive controller marked with a CE logo comply with the requirements specified by European Union guidelines. The CE Declaration of Conformity is available on the Internet at www.keb-automation.com/de/suche .



For further information regarding the CE declarations of conformity

=> „7.3 Further informations and documentation“

7.2 UL certification

	Acceptance according to UL is marked at KEB drive converters with the adjacent logo on the nameplate.	UL file number E167544
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To be conform according to UL for use on the North American and Canadian Market the following additionally instructions must be observed (original text of the UL-File):

- All models:
Maximum Surrounding Air Temperature: 45°C
- Use 75°C Copper Conductors Only

This marking is only applicable for all power field wiring terminals.

- Control Circuit Overcurrent Protection Required
- Brake resistor ratings and duty cycle:
 - Duty cycle 50%
 - Max. 60 sec on-time (60 sec off-time)
- For the DC bus terminals and the mains/motor terminals, the installation instructions or user maintenance manual shall identify any accessible part at voltages greater than DVC A, and shall describe insulation and separation provisions required for protection.
- All models: „Suitable For Use On A Circuit Capable Of Delivering Not More Than 18000 rms Symmetrical Amperes, 480 Volts Maximum when protected by Class J Fuses, see instruction manual for Branch Circuit Protection details.”

CSA: For Canada:

Integral solid state short circuit protection does not provide branch circuit protection. Branch circuit protection must be provided in accordance with the Canadian Electrical Code, Part I.

LA PROTECTION INTÉGRÉE CONTRE LES COURTSCIRCUITS N'ASSURE PAS LA PROTECTION DE LA DÉRIVATION. LA PROTECTION DE LA DÉRIVATION DOIT ÊTRE EXÉCUTÉE CONFORMÉMENT AU CODE CANADIEN DE L'ÉLECTRICITÉ, PREMIÈRE PARTIE.

- For Use in a Pollution Degree 2 environment
For installations according to Canadian National Standard C22.2 No. 274-13:
For use in Pollution Degree 2 and Overvoltage Category III environments only

- **WARNING** – The opening of the branch circuit protective device may be an indication that a fault current has been interrupted. To reduce the risk of fire or electrical shock, current-carrying parts and other components of the controller should be examined and replaced if damaged. If burnout of the current element of an overload relay occurs, the complete overload relay must be replaced.”

CSA: For Canada:

“ATTENTION - LE DÉCLENCHEMENT DU DISPOSITIF DE PROTECTION DU CIRCUIT DE DÉRIVATION PEUT ÊTRE DÙ À UNE COUPURE QUI RÉSULTE D'UN COURANT DE DÉFAUT. POUR LIMITER LE RISQUE D'INCENDIE OU DE CHOC ÉLECTRIQUE, EXAMINER LES PIÈCES PORTEUSES DE COURANT ET LES AUTRES ÉLÉMENTS DU CONTRÔLEUR ET LES REMPLACER S'ILS SONT ENDOMMAGÉS. EN CAS DE GRILLAGE DE L'ÉLÉMENT TRAVERSÉ PAR LE COURANT DANS UN RELAIS DE SURCHARGE, LE RELAIS TOUT ENTIER DOIT ÊTRE REMPLACÉ.

- For high performance:
 - Maximum working pressure: 10 bar (145 psi)
 - Max. inlet liquid temperature: +55°C
 - Min. liquid flow rate: 20 l/min
 - Water or a mixture of water with a maximum of 52% monoethylene glycol

7.3 Further informations and documentation

You find supplementary manuals and instructions for the download under www.keb-automation.com/search

General instructions

- EMC and safety instructions
- Manuals for additional control boards, safety modules, fieldbus modules, etc.

Instruction and information for construction and development

- Input fuses in accordance with UL
- Programming manual for control and power unit
- Motor configurator to select the appropriate drive converter and to create downloads for parameterizing the drive converter

Approvals and approbations

- Declaration of conformity CE
- TÜV certificate
- FS certification

Other markings and approvals not listed here are identified by a corresponding logo on the rating plate or device, if applicable. The corresponding certificates are available on our website.

Others

- COMBIVIS, the software for comfortable parameterization of drive converters via PC (available per download)
- EPLAN drawings

8 Revision history

Version	Date	Description
00	2023-10	Creation of the pre-series manual
01	2023-12	Inclusion of water-cooled devices
02	2024-07	Inclusion of the UL approval, creation of the series version
03	2025-11	Description of DC-Ready devices included. Glossary and standards updated, editorial changes.

Glossary

0V	Earth-potential-free common point	Encoder emu- lation	Software-generated encoder output
1ph	1-phase mains	End customer	The end customer is the user of the customer product
3ph	3-phase mains	Endat	Bidirectional encoder interface of the company Heidenhain
AC	AC current or voltage	EtherCAT	Real-time Ethernet bus system of the company Beckhoff
AFE	From 07/2019 AIC replaces the previous name AFE	Ethernet	Real-time bus system - defines protocols, plugs, types of cables
AFE filter	From 07/2019 AIC filter replaces the previous name AFE filter	FE	Functional earth
AIC	Active Infeed Converter	FSoE	Functional Safety over Ethernet
AIC filter	Filter for Active Infeed Converter	FU	Drive controller
Application	The application is the intended use of the KEB product	GND	Reference potential, ground
ASCL	Asynchronous sensorless closed loop	GTR7	Braking transistor
Auto motor ident.	Automatically motor identification; calibration of resistance and inductance	HF filter	KEB specific term for an EMC filter (for description see EMC filter).
AWG	American wire gauge	Hiperface	Bidirectional encoder interface of the company Sick-Stegmann
B2B	Business-to-business	HMI	Human machine interface (touch screen)
BiSS	Open source real-time interface for sensors and actuators (DIN 5008)	HSP5	Fast, serial protocol
CAN	Fieldbus system	HTL	Incremental signal with an output voltage (up to 30V) -> TTL
c.d.f.	Cyclic duration factor	IEC	IEC xxxxx stands for an international standard of the International Electro-technical Commission
CDM	Complete drive module including auxiliary equipment (control cabinet)	IPxx	Protection class (xx for class)
COMBIVERT	KEB drive controller	KEB product	The KEB product is subject of this manual
COMBIVIS	KEB start-up and parameterizing software	KTY	Silicium temperature sensor (polarized)
Customer	The customer has purchased a KEB product from KEB and integrates the KEB product into his product (customer product) or resells the KEB product (dealer)	Manufacturer	The manufacturer is KEB, unless otherwise specified (e.g. as manufacturer of machines, engines, vehicles or adhesives)
DC	DC current or voltage	MCM	American unit for large wire cross sections
DI	Demineralized water, also referred to as deionized (DI) water	Modulation	Means in drive technology that the power semiconductors are controlled
DIN	German Institut for standardization	MTTF	Mean service life to failure
DS 402	CiA DS 402 - CAN device profile for drives	NHN	Standard elevation zero; based on the specified height definition in Germany (DHHN2016). The international data generally deviate from this by only a few cm to dm, so that the specified value can be applied to the regionally applicable definition.
ELV	Extra-low voltage	OC	Overcurrent
EMC filter	EMC filters are used to suppress conducted interferences in both directions between the drive controller and the mains	OH	Overheat
Emergency stop	Shutdown of a drive in emergency case (not de-energized)	OL	Overload
Emergency switching off	Switching off the voltage supply in emergency case		
EMS	Energy Management System		
EN	European standard		

OSSD	Output signal swithching device; - an output signal that is checked in regular intervals on its shutdown. (safety technology)
PDS	Power drive system incl. motor and measuring probe
PE	Protective earth
PELV	Protective Extra Low Voltage
PF	Term used in the safety technology (EN 61508-1...7) for the size of error probability
PFH	Term used in the safety technology (EN 61508-1...7) for the size of error probability per hour
PLC	Programmable logic controller
Pt100	Temperature sensor with R0=100Ω
Pt1000	Temperature sensor with R0=1000Ω
PTC	PTC-resistor for temperature detection
PWM	Pulse width modulation
RJ45	Modular connector with 8 lines
SCL	Synchronous sensorless closed loop
SELV	Safe extra-low voltage, unearthed
SIL	The safety integrity level is a measure for quantifying the risk reduction. Term used in the safety technology (EN 61508 -1...7)
SS1	Safety function „Safe stop 1“ in accordance with IEC 61800-5-2
SSI	Synchronous serial interface for encoder
STO	Safety function „Safe Torque Off“ in accordance with IEC 61800-5-2
TTL	Logic with 5 V operating voltage
USB	Universal serial bus
VARAN	Real-time Ethernet bus system

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